

# Motor Driver ICs

## Power Dissipation and PCB Layout

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# Motor Drivers – Power Dissipation and PCB Design

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Introduction to Motor Driver ICs

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Power Dissipation in Drivers

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PCB Design for Power Dissipation

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Summary / Q&A

# An Introduction to Motor Driver ICs



**Brushed DC Motor**

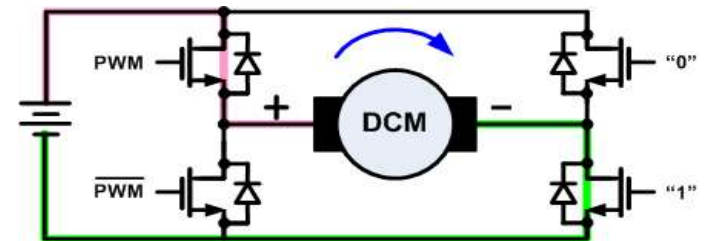
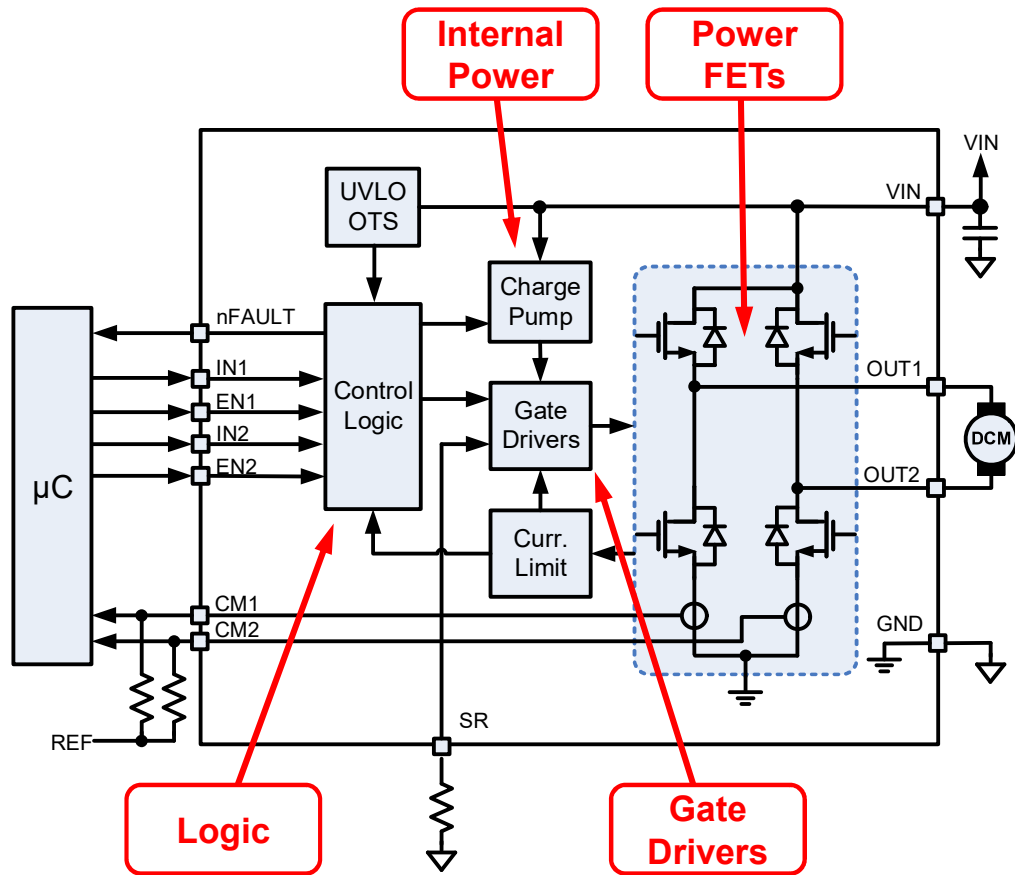


**Brushless DC Motor**



**Stepper Motor**

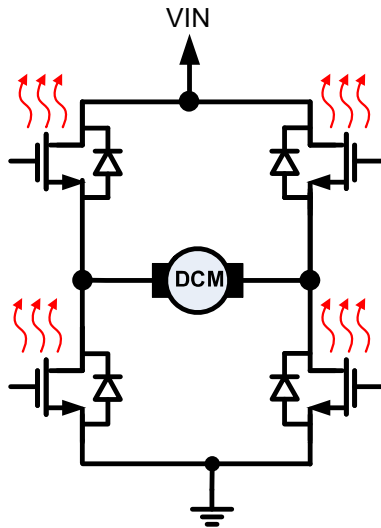
# Inside a DC Motor Driver IC



# Power Dissipation in Motor Drivers

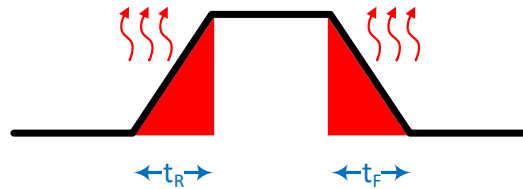
## Resistive Losses

$$P_R = I^2 R$$



## Switching Losses

$$P_S \approx \frac{1}{2} \times V \times I \times f_{sw} \times t_R + \frac{1}{2} \times V \times I \times f_{sw} \times t_F$$



## Static Losses

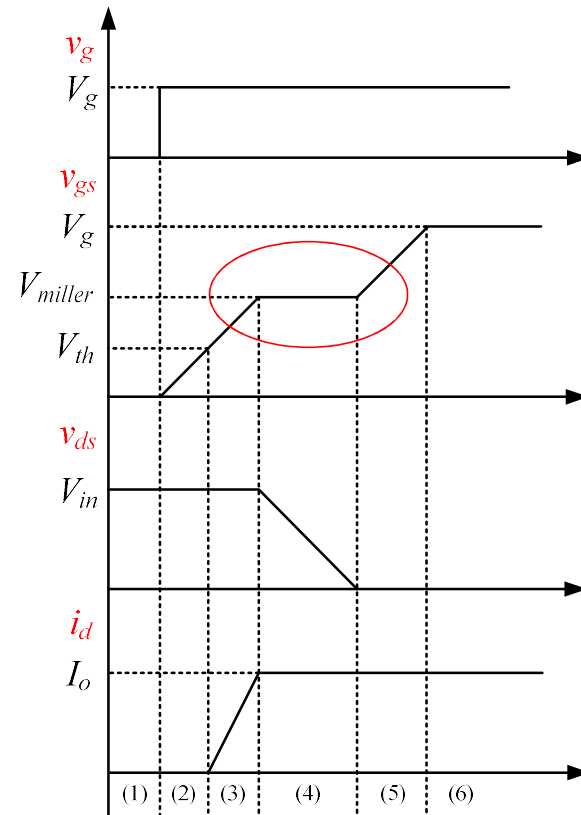
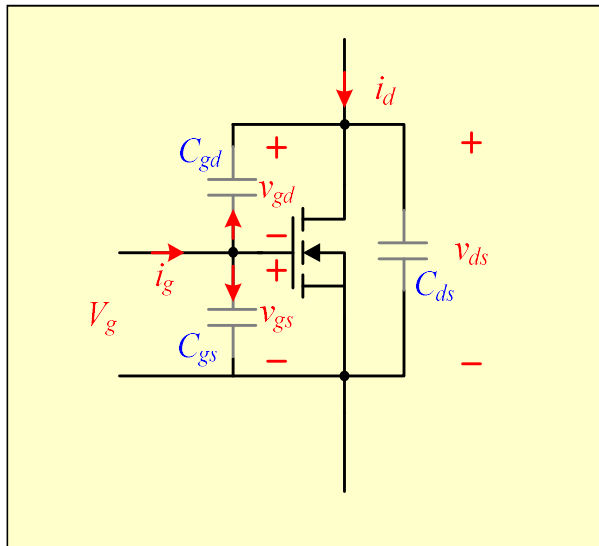
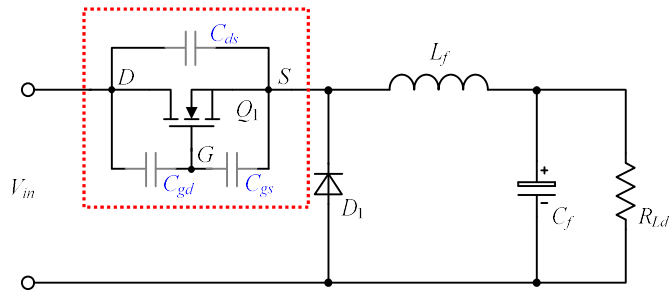
$$P_Q = V_{IN} \times I_Q$$



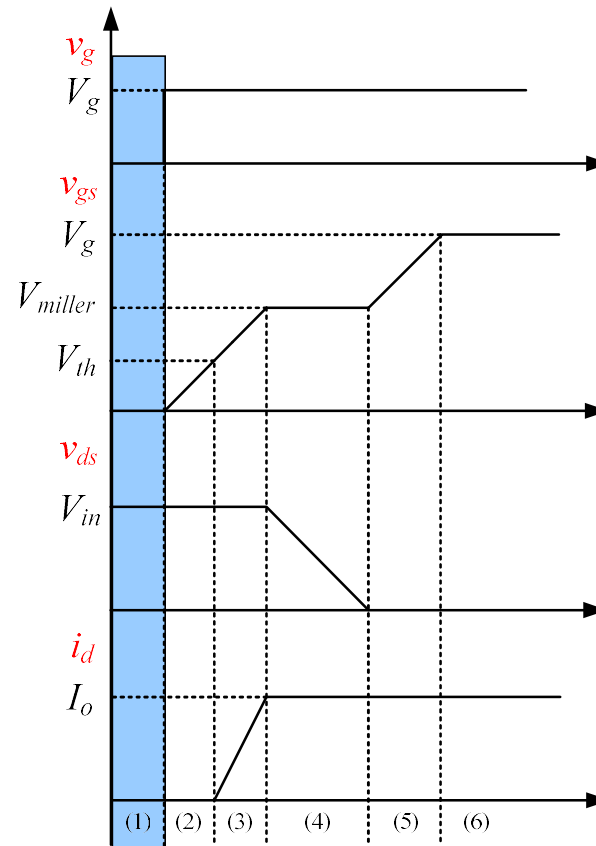
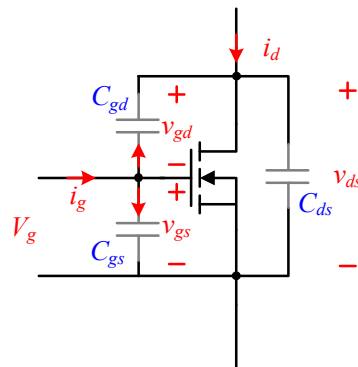
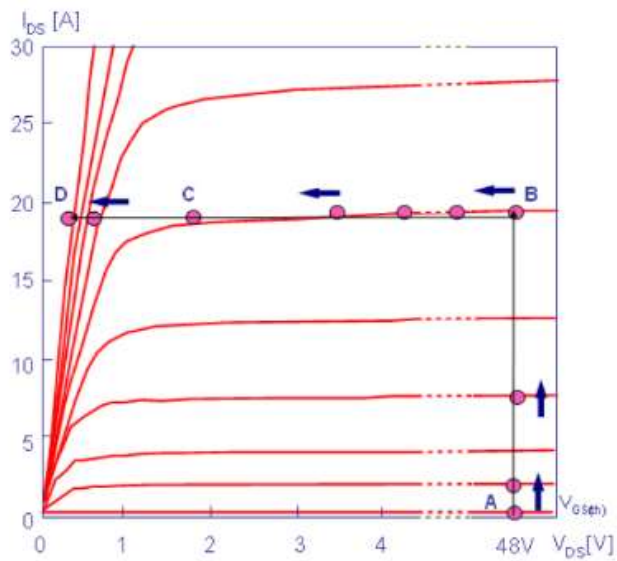
## Total Power

$$P = P_R + P_S + P_Q$$

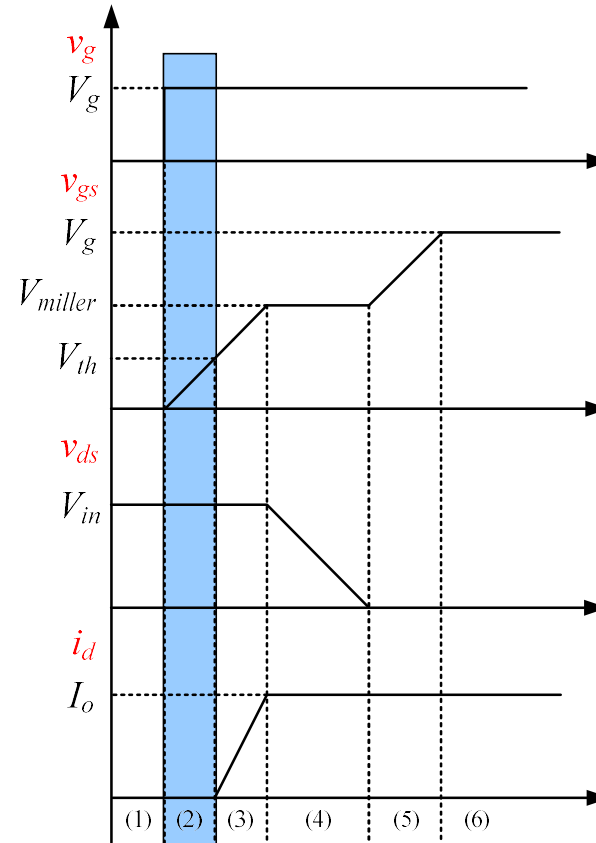
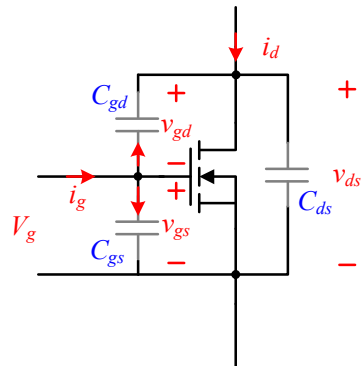
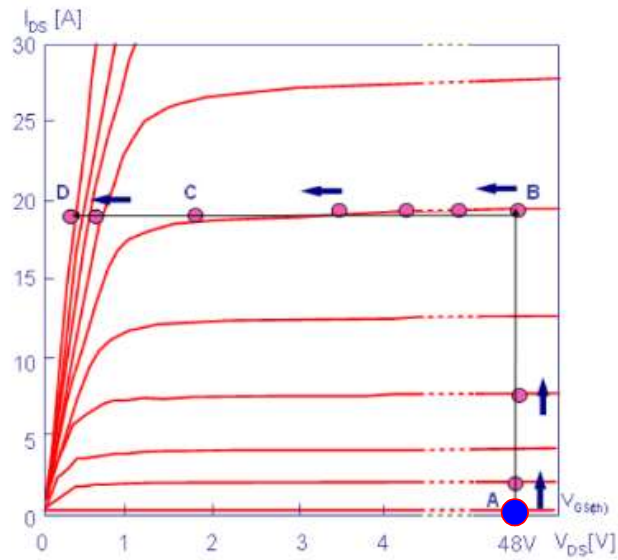
# MOSFET Turn On Process



# MOSFET Turn On Process

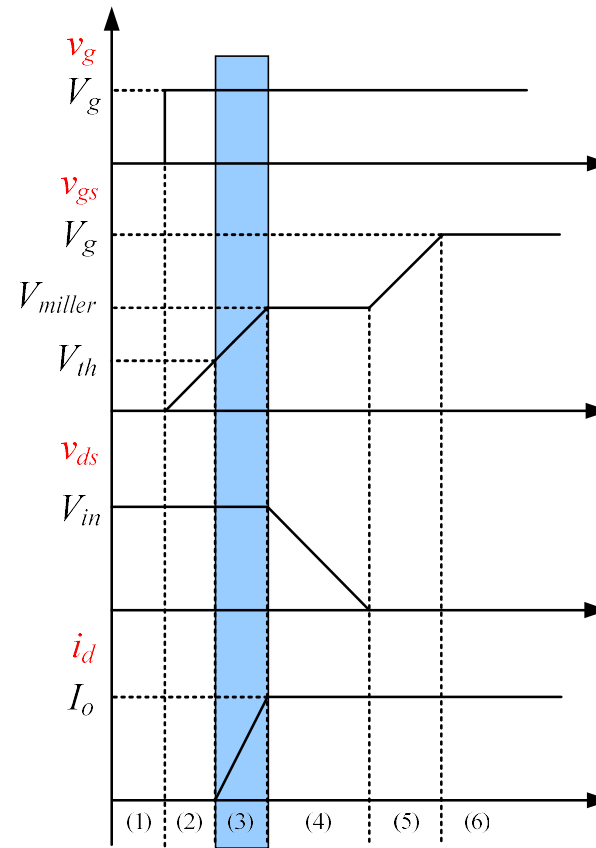
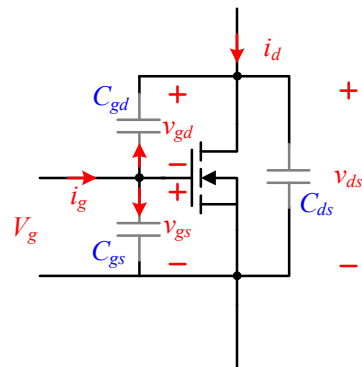
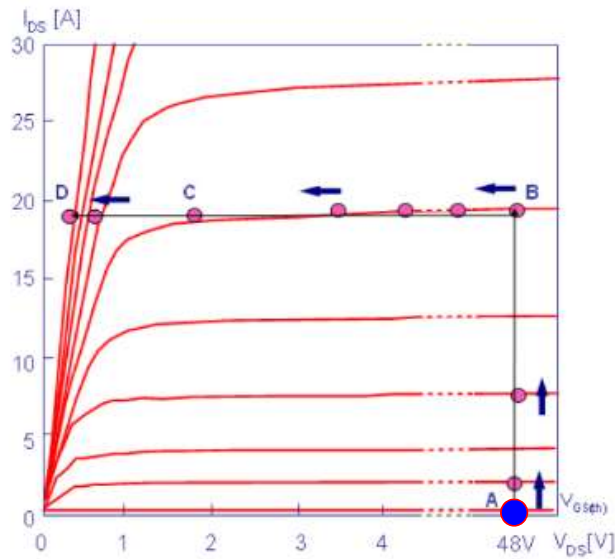


# MOSFET Turn On Process

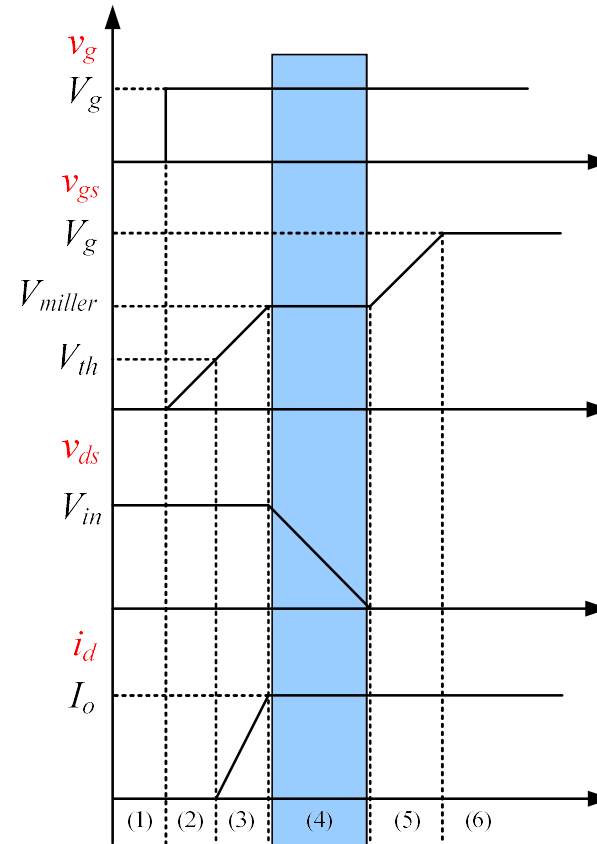
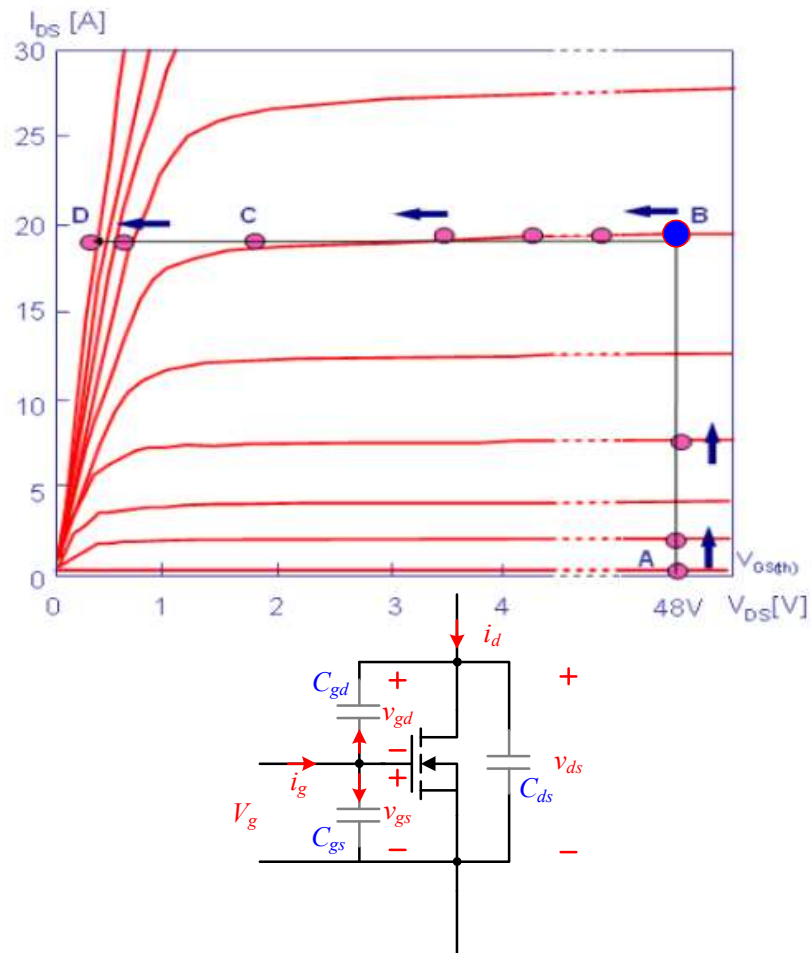




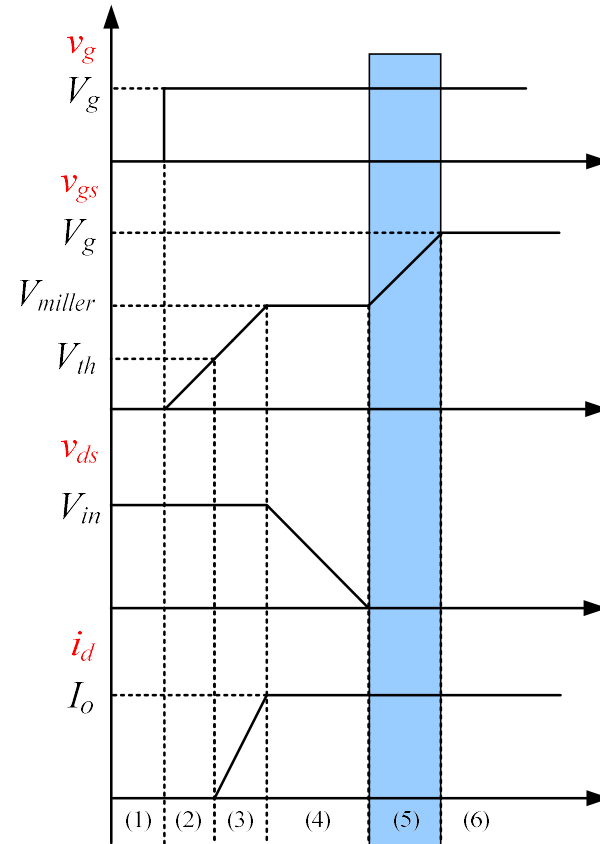
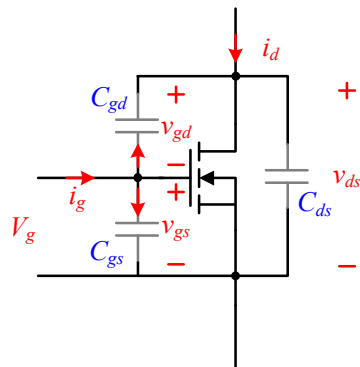
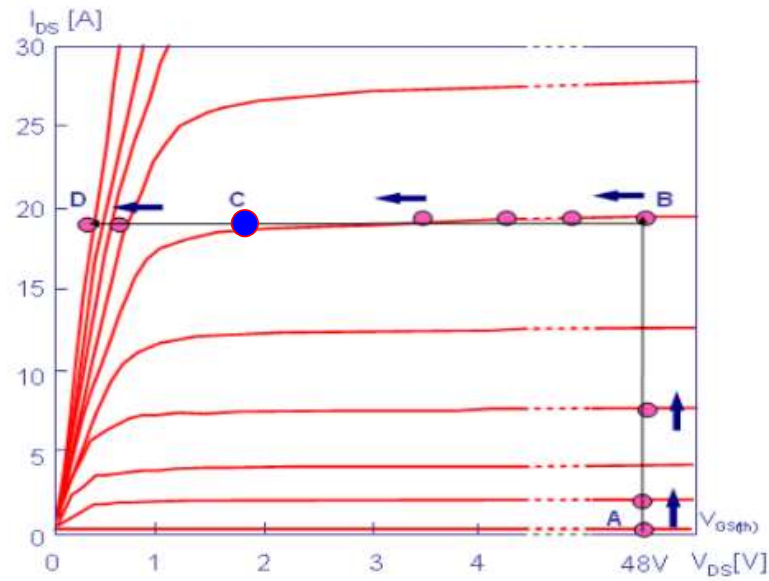
# MOSFET Turn On Process



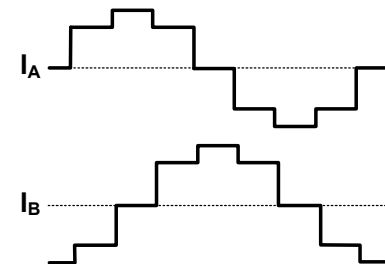
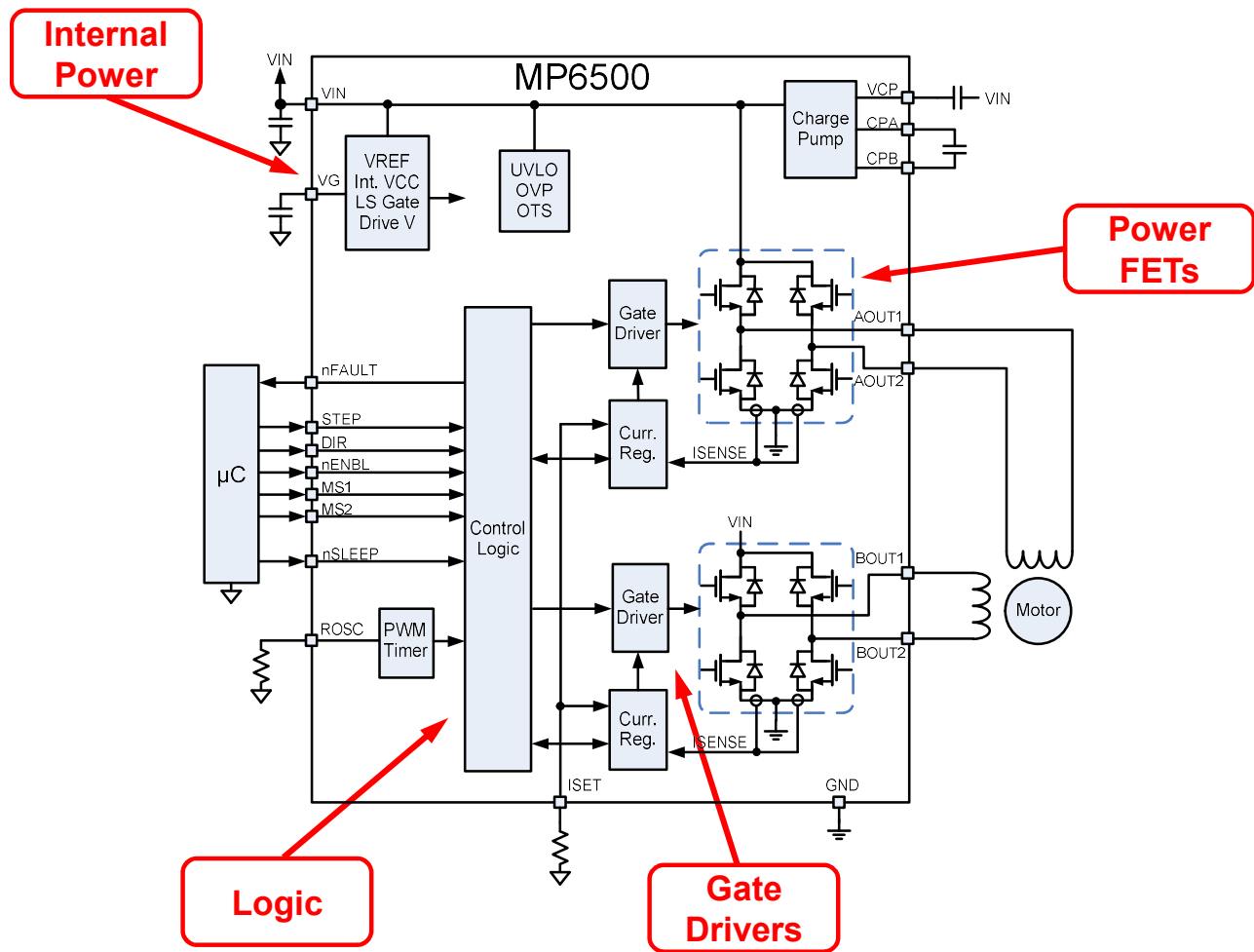
# MOSFET Turn On Process



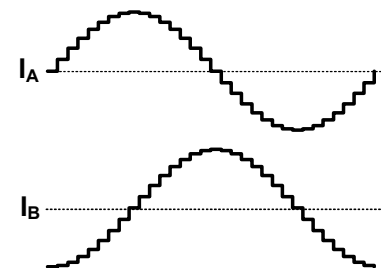
# MOSFET Turn On Process



# Power Dissipation in Stepper Motor Driver ICs

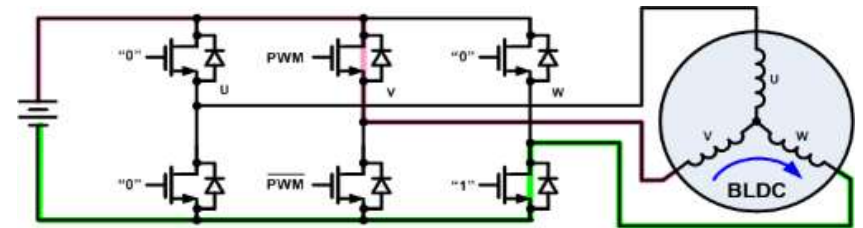
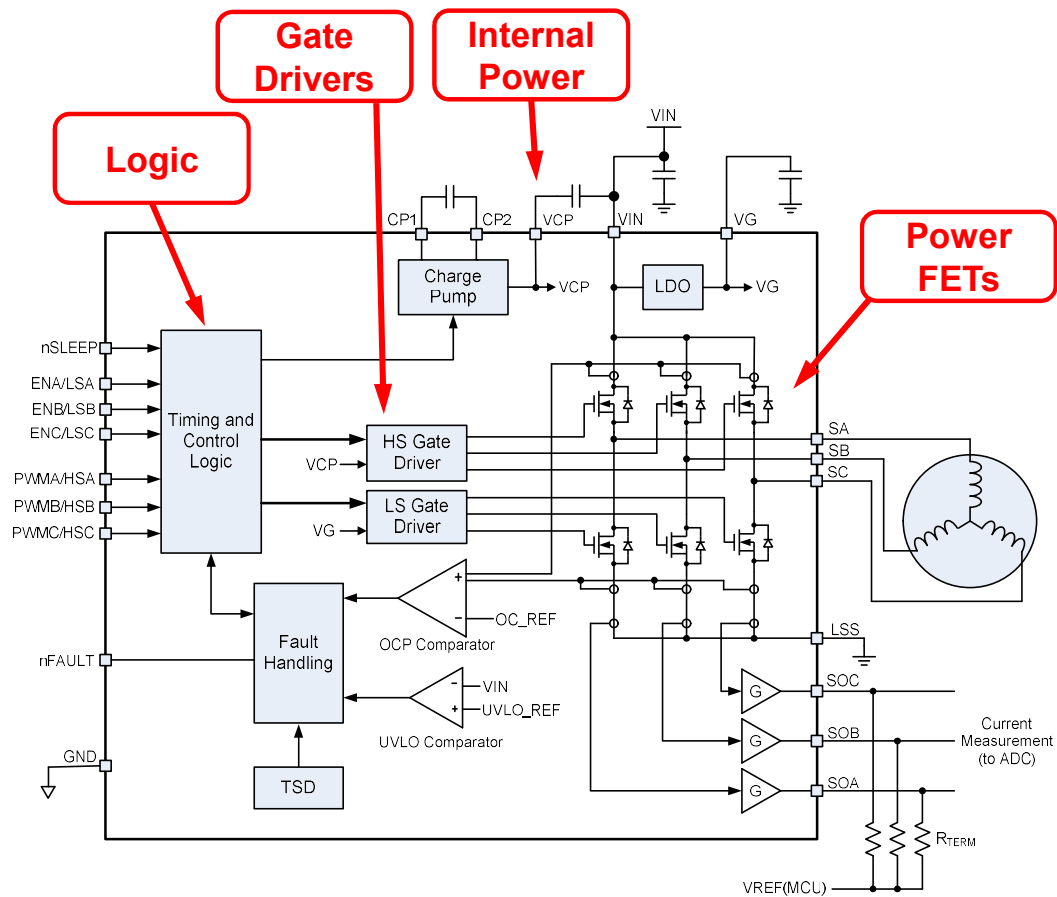


8 Segments  
Half-Step



32 Segments  
Eighth-Step

# Brushless Motor Drivers



## Power Dissipation Example

Using the MP6550 IC as an example:

HS Switch-On Resistance	R <sub>DS(ON)</sub>	IO=800mA, Ta = 25°C,	0.1	0.13	Ω
LS Switch-On Resistance	R <sub>DS(ON)</sub>	IO=800mA, Ta = 25°C,	0.1	0.13	Ω

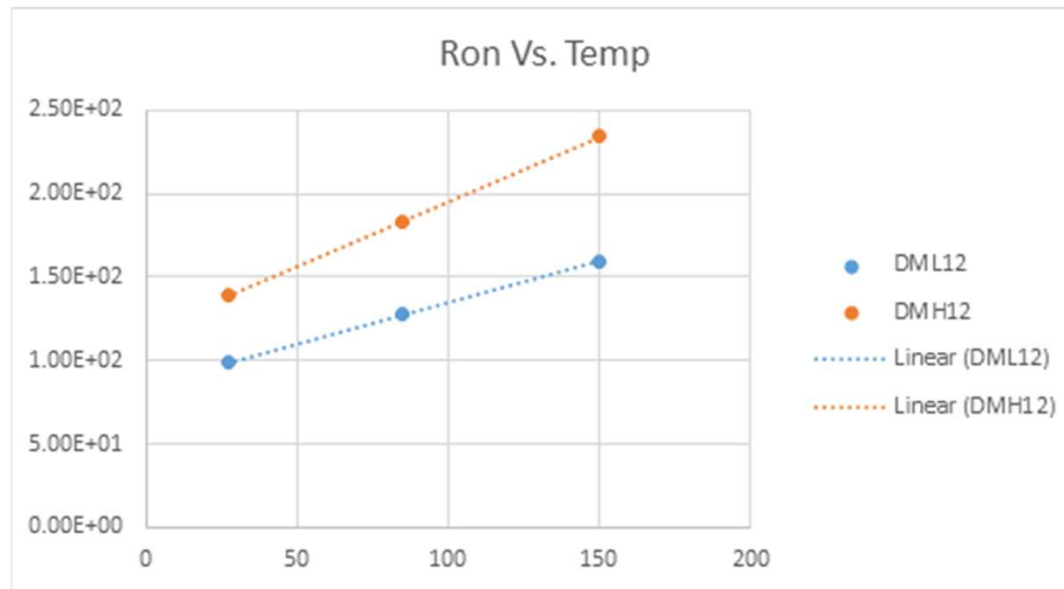
Operating supply current		no PWM, no load, nSLEEP_HB = 5V, nSLEEP_LDO = 0	0.85	1.1	mA
		50-kHz PWM, no load, nSLEEP_HB = 5V, nSLEEP_LDO = 0	1.2	1.5	mA

Output rise time		RL = 20Ω		100	ns
Output fall time		RL = 20Ω		100	ns

Let's assume you are driving a load with 5V, 2A output current with a PWM frequency of:

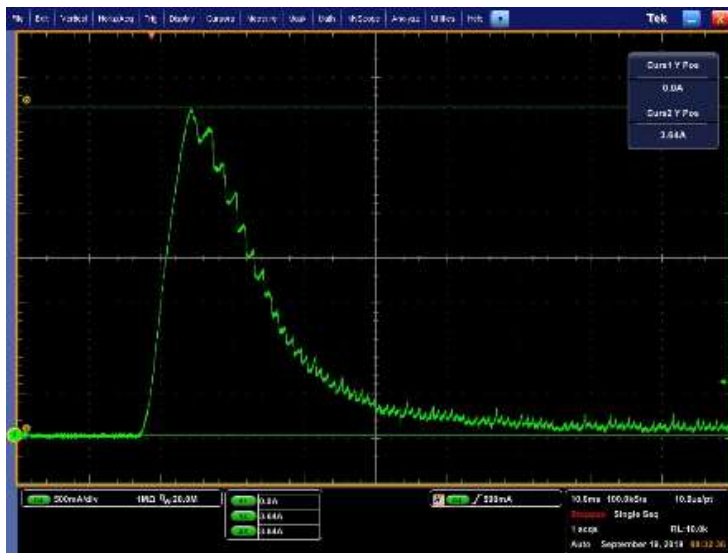
- Using the  $R_{DS(ON)}$ , we will dissipate  $(2A)^2 \times 0.1\Omega = 0.4W$  in the high side, and  $(2A)^2 \times 0.1\Omega = 0.4W$  in the low side
- Static power will be  $5V \times 1.2mA = 0.006W$
- Switching loss is approximately  $(1/2 \times 100ns \times 50kHz \times 5V \times 2A) + (1/2 \times 100ns \times 50kHz \times 5V \times 2A) = 0.05W$
- Total power is then 0.856W

## A Problem: $R_{DS(ON)}$ vs. Temperature



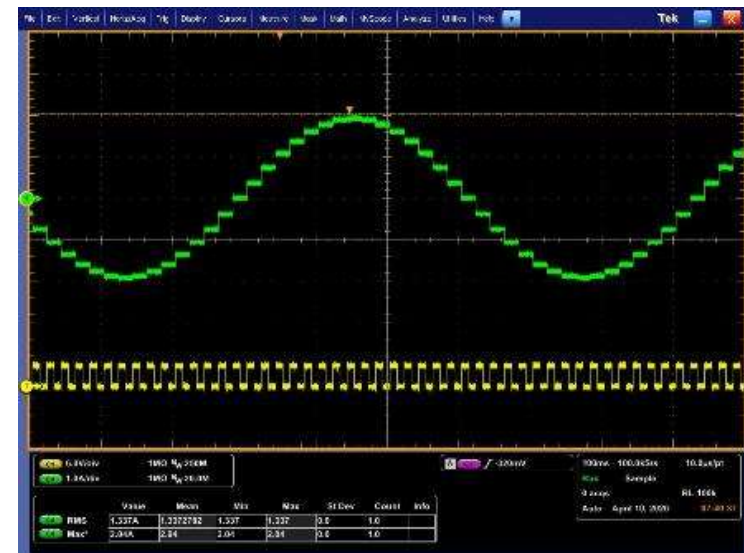
# Peak vs. Average and RMS Load Current

## DC Motor Start-Up Current



3.6A Peak for ~20ms

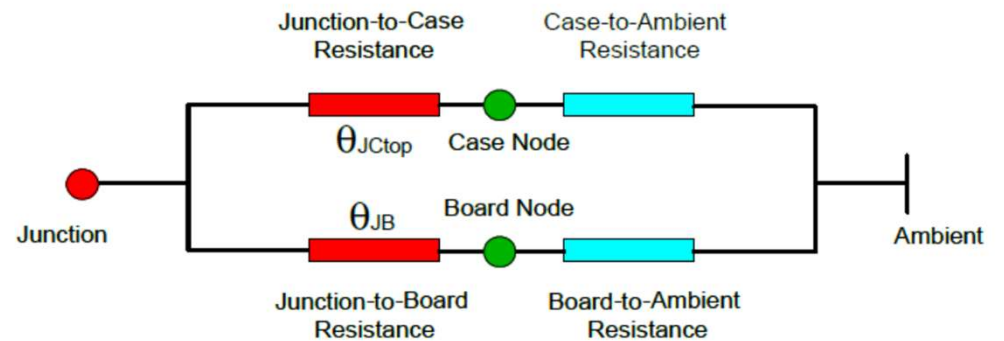
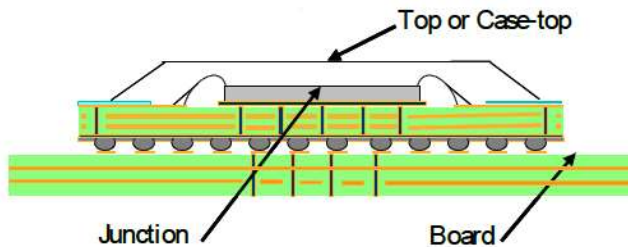
## Stepper Motor RMS Current



2A peak  $\approx$  1.4A RMS



# Thermal Resistance & Models



Continuous Power Dissipation ( $T_A = +25^\circ\text{C}$ ) <sup>(2)</sup>  
.....1.56W  
Junction Temperature .....150°C

**Simple Estimation:**  
**Die temperature = ambient temp + ( $P \times \theta_{JA}$ )**

# Temperature Rise Example

Using the MP6550 IC as an example:

**Thermal Resistance** <sup>(4)</sup>       $\theta_{JA}$        $\theta_{JC}$   
 QFN-12 (2mm×2mm)..... 80 ..... 16..... °C/W

Continuous Power Dissipation ( $T_A = +25^\circ\text{C}$ ) <sup>(2)</sup>  
 ..... 1.56W

Thermal shutdown threshold <sup>(6)</sup>	$T_{TSD}$			160		°C
Thermal shutdown hysteresis <sup>(6)</sup>				25		°C

Total power dissipation is 0.856W:

- Temperature rise is  $P \times \theta_{JA}$ , so  
 $0.856 \times 80 = 68.48^\circ\text{C}$
- Junction temperature is  $T_A + T_R$ .

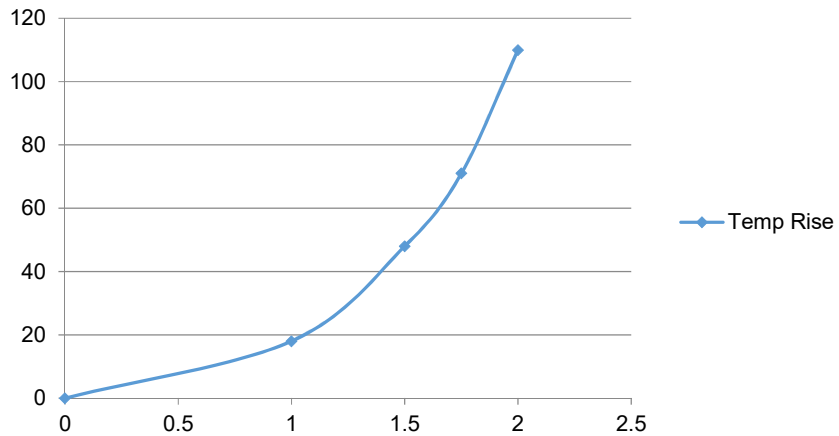
If we assume room temperature of  $25^\circ\text{C}$ , then the junction is at  $25 + 68.48 = 93.48^\circ\text{C}$ .

If the ambient is  $70^\circ\text{C}$ , then the junction temperature will be  $138.48^\circ\text{C}$ .

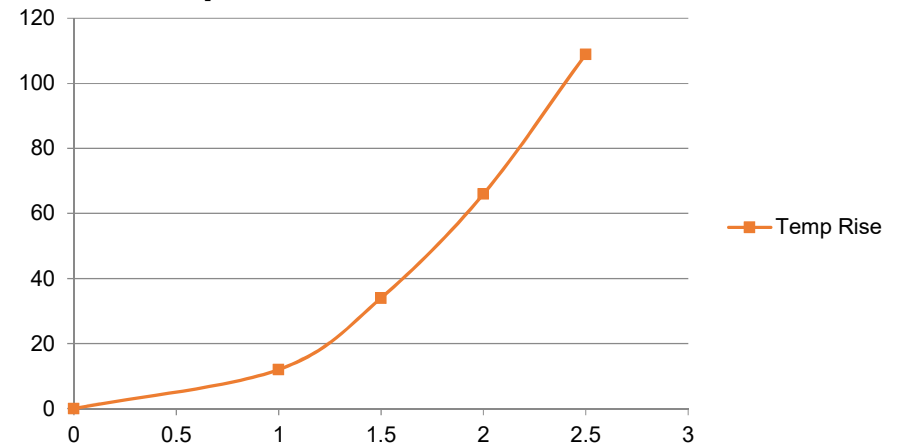
# Temperature Rise vs. Output Current

**Bigger Package = Better Thermals**

**Temp Rise MP6600 QFN**



**Temp Rise MP6500 TSSOP**



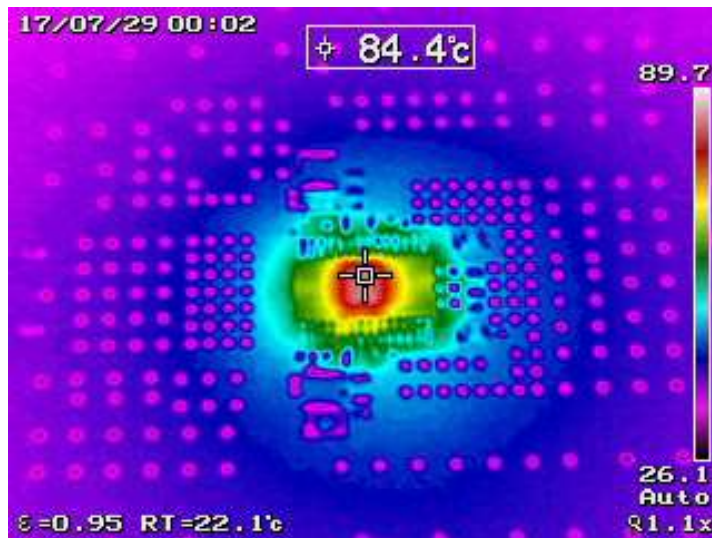
# PCB Design for Power Dissipation

**Table 7 — JESD51-7 High Thermal Conductivity Leaded SMT Test Board Parameters [8]**

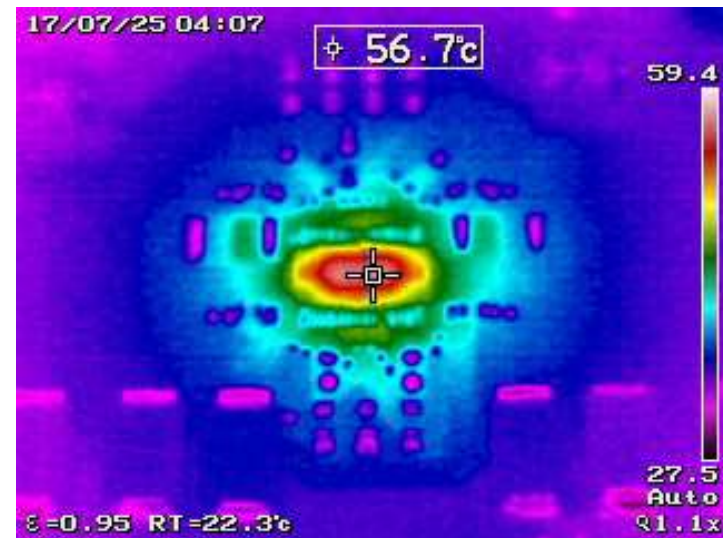
Dimension	Specification	User
Board Finish Thickness	1.60 mm $\pm$ 10%	
Board Dimension (pkg length < 27 mm)	76.2 mm x 114.3 mm	
Board Dimension (27 mm $\leq$ pkg length $\leq$ 48 mm)	101.6 mm x 114.3 mm	
Board material	FR-4	
Trace Copper Thickness	0.070 mm $\pm$ 20%	
Trace Width, Finished	0.25 mm $\pm$ 10% for $\geq$ 0.50 mm pin pitch Lead width for < 0.50 mm pin pitch	
Trace Coverage Area (Total)		
Power/Ground Thickness	35 $\mu$ m (1oz) copper +0/-20%	

## Effect of Layer Count & Planes

MP6500 Driving 2A Peak Stepper Motor

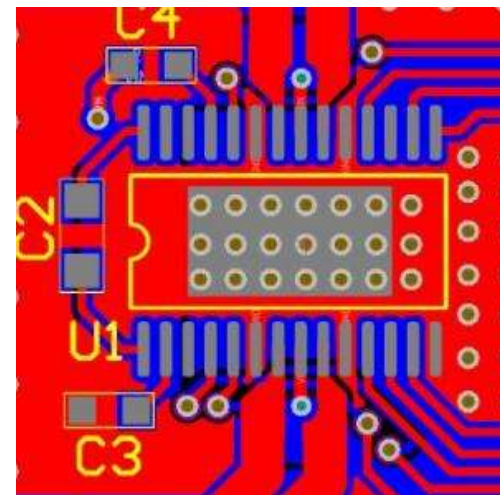
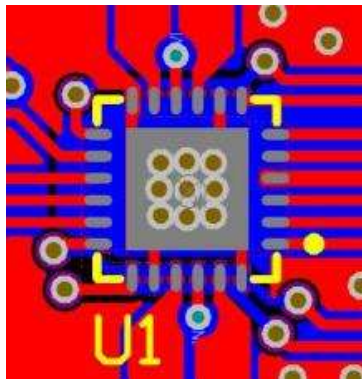
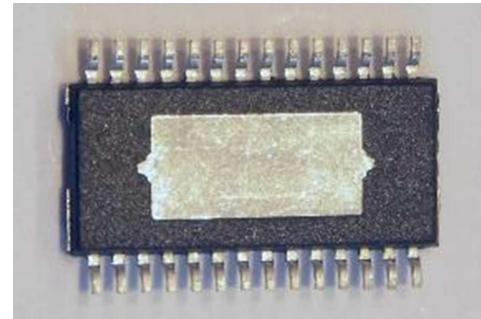


2 Layers

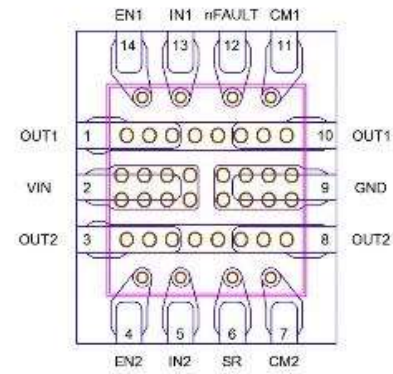
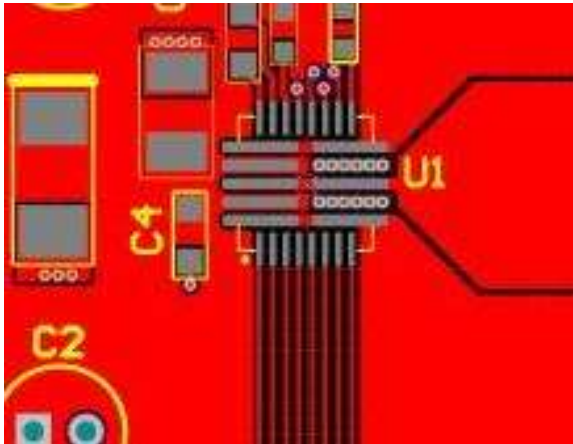
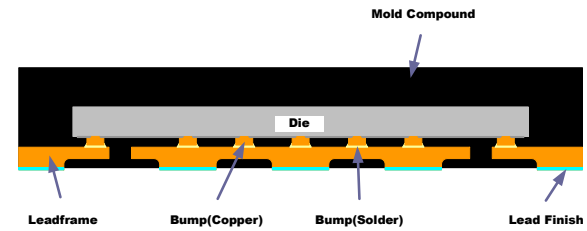
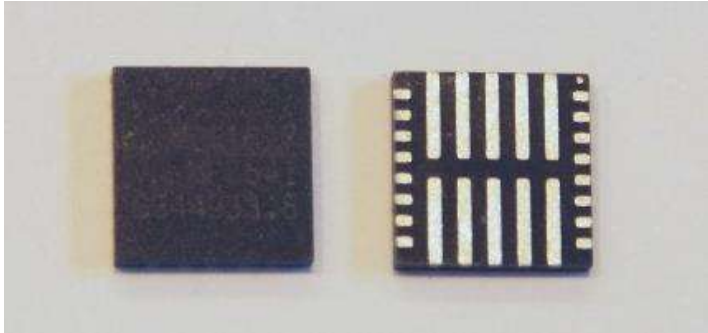


4 Layers (2 Planes)

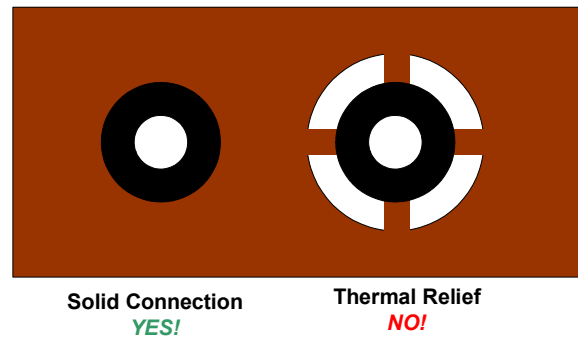
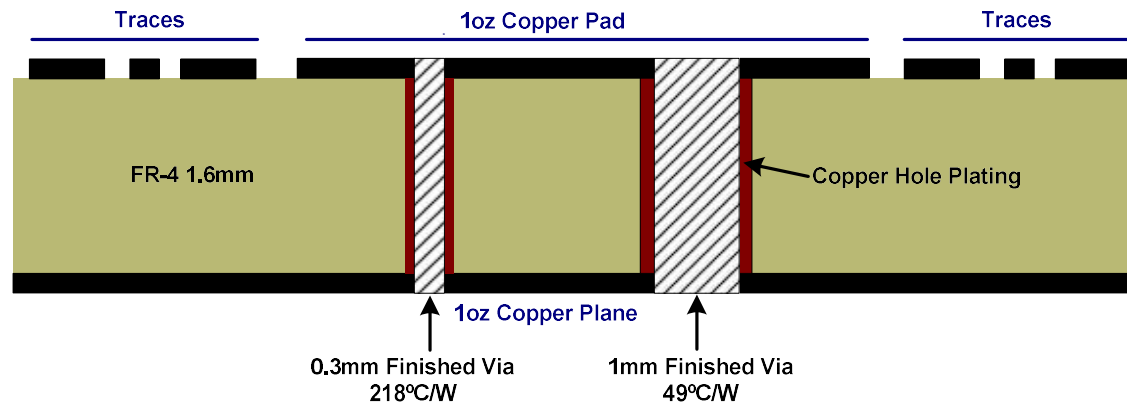
## Exposed Pads on TSSOP & QFN



# Flip-Chip QFN and LGA Packages



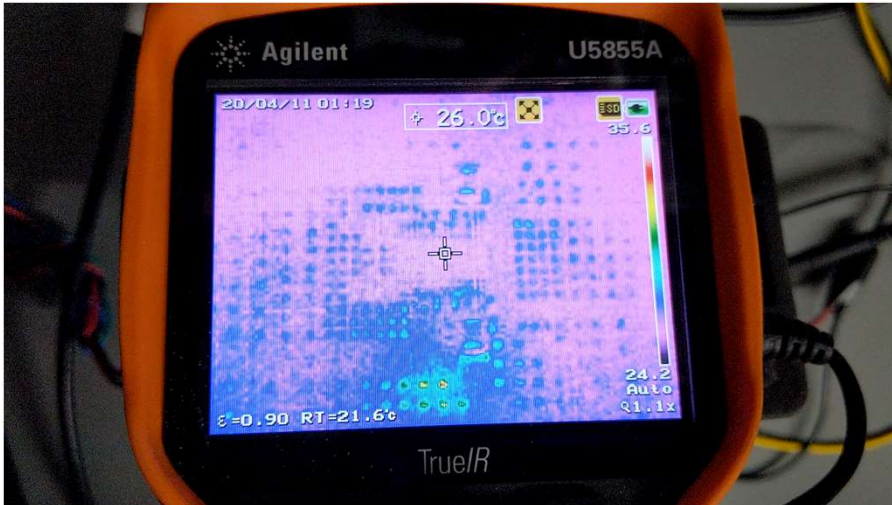
# Thermal Vias





## What Happens if the Exposed Pad isn't Soldered?

**MP6500 Driving 2A Peak Stepper Motor  
4-Layer PCB**



**Exposed Pad Soldered**



**Exposed Pad Not Soldered**

## Summary

- Calculate the power dissipated in your motor driver IC
  - Or work backwards and calculate maximum current from thermal conditions
- Minimize thermal resistance
  - Bigger is always better
  - Multi-layer boards work best
- Use thermal vias to spread heat
- ALWAYS solder the exposed pad