

# MPS新的中大功率ACDC电源方案分享

Nov 2021

丁连锋

**MPS**

# ACDC电源产品应用领域

<100W



>100W



MPS

# ACDC电源产品的要求

高效

高功率密度

有竞争力的BOM

高可靠性

无电磁兼容问题



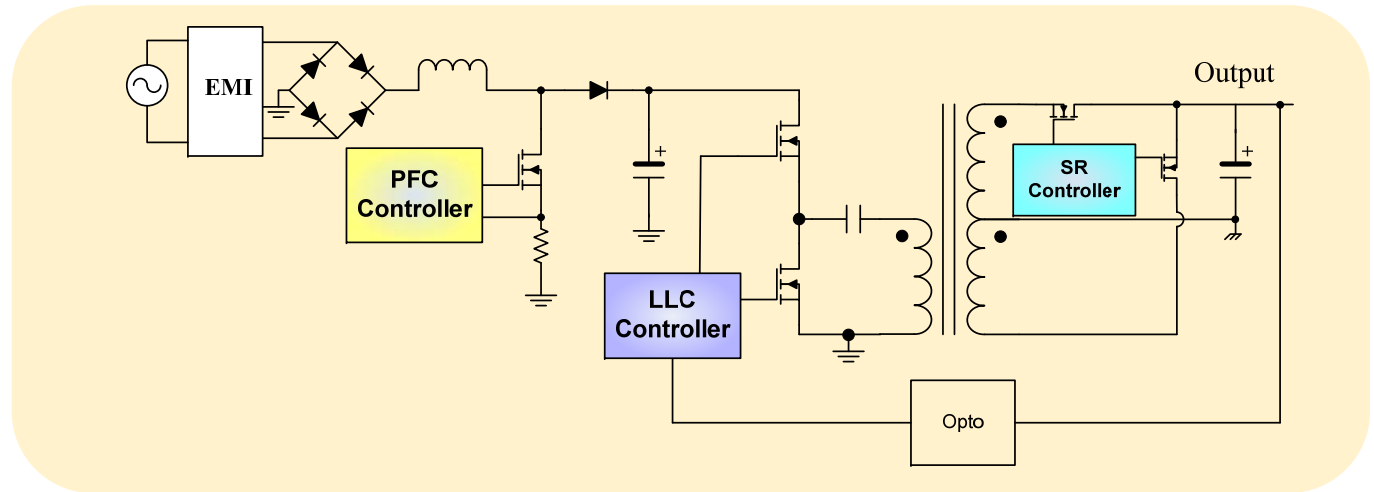
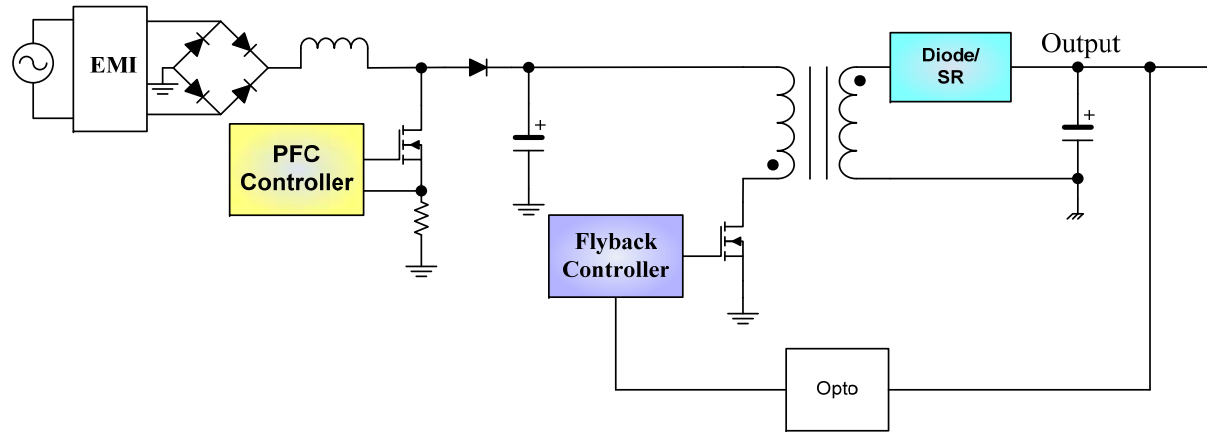
# 中大功率ACDC电源方案

Power > 75W, 电源方案都需要加PFC

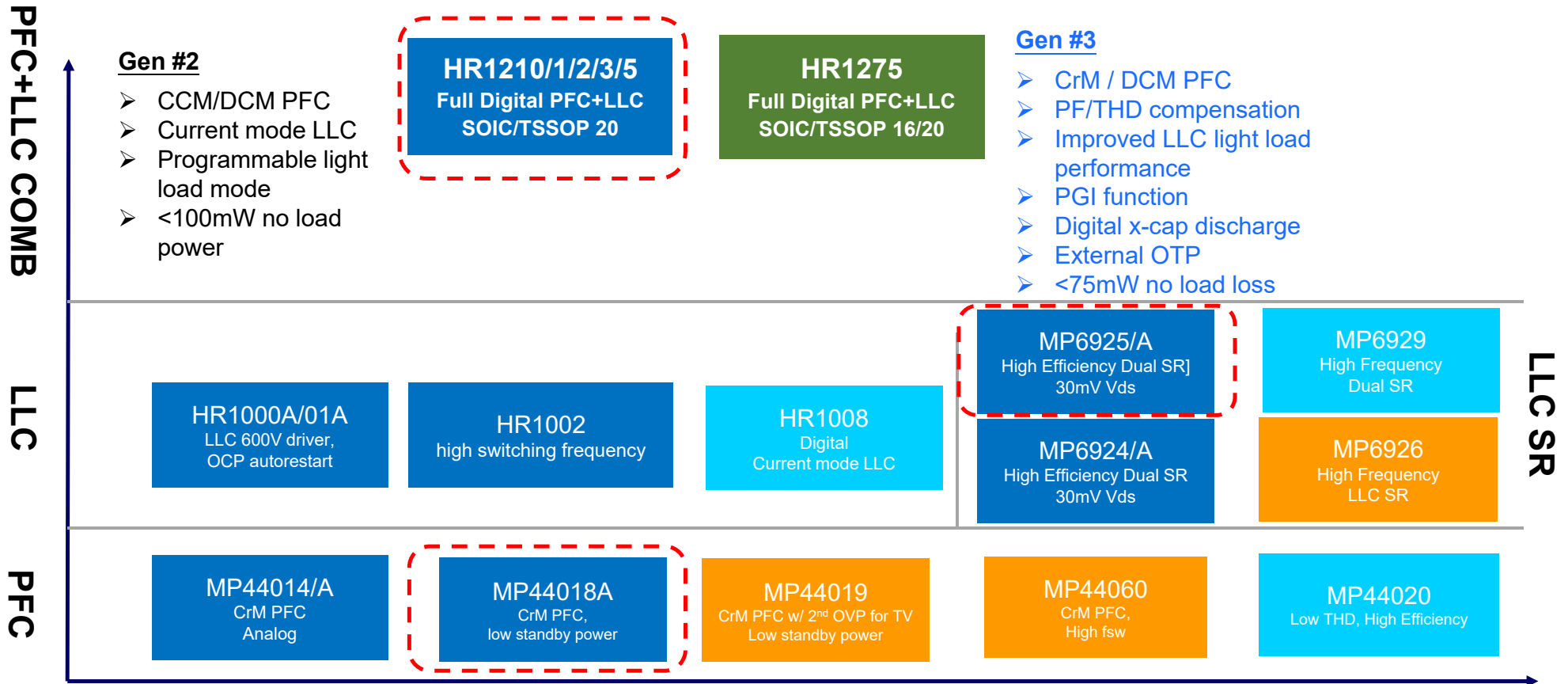
比较常见的电源方案:

PFC+Flyback (<150W)

**PFC+LLC (>100W)**



# MPS 中大功率ACDC电源方案



Released

Sampling

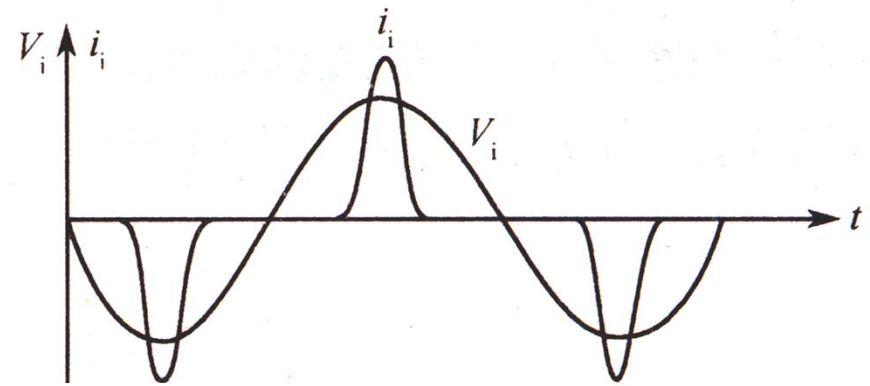
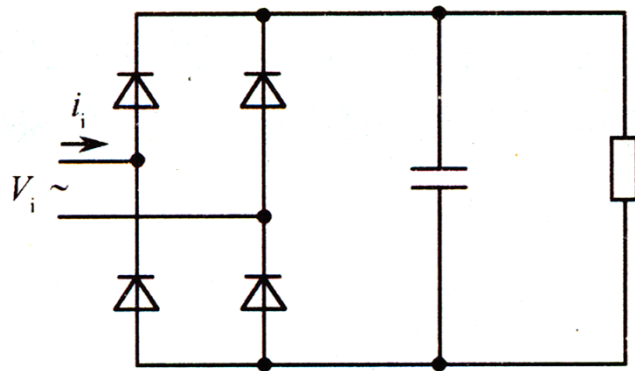
Under Design

Concept



# 高性能的PFC方案

# PFC的目的



$$PF = \frac{P_{\text{有功}}}{P_{\text{视在}}} = \frac{V_{1rms} \times I_{1rms} \cos \varphi}{V_{rms} \times I_{rms}} = \frac{I_{1rms} \cos \varphi}{I_{rms}} = \gamma \cos \varphi$$

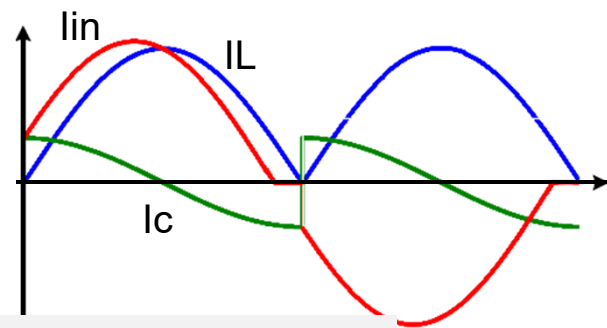
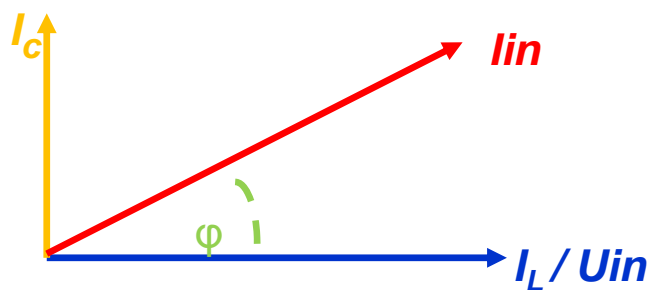
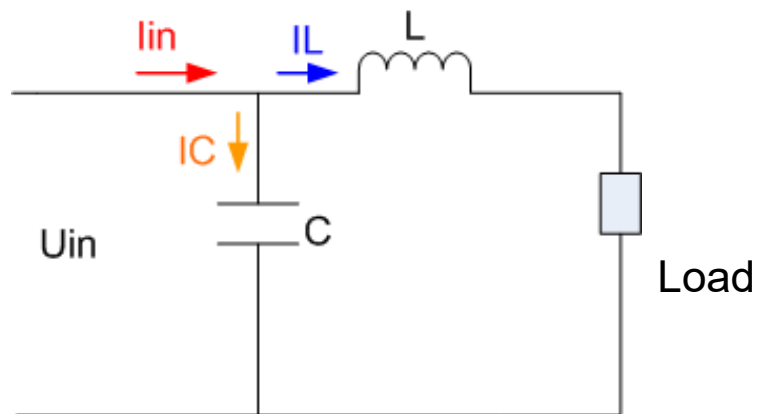
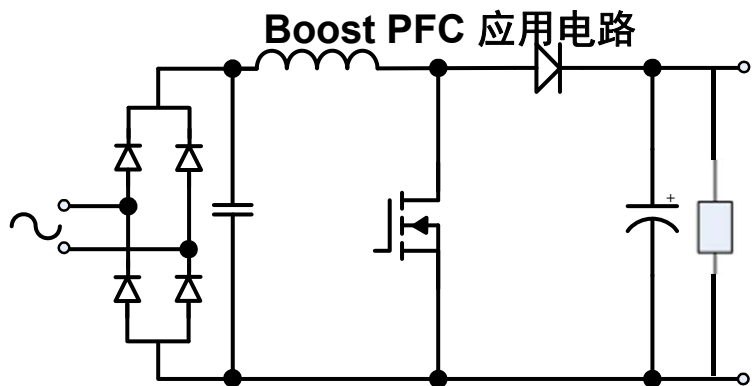
$\gamma$ 基波因数  $\cos \varphi$ 基波功率因数

$$\gamma = \frac{I_{1rms}}{I_{rms}} = \frac{I_{1rms}}{\sqrt{\sum_1^n I_{krms}^2}} = \frac{1}{\sqrt{1 + \text{THD}^2}}$$

➤ **PF=1**

1. 将输入电流波形尽量校正成正弦波形，减少谐波失真  $\gamma=1$  -----》 **THD=0**
2. 输入电流和输入电压尽量同相位  $\cos \varphi=1$

# 影响有源功率因数校正的参数



➤ 改善PF  $\cos \varphi = \frac{P_{in} / U_{in}}{\sqrt{(P_{in} / U_{in})^2 + (U_{in} \times \omega C)^2}}$

1. 减小THD -----> 优化输入电流波形

2. 减小相位差 -----> 减小输入电容或者补偿容性电流



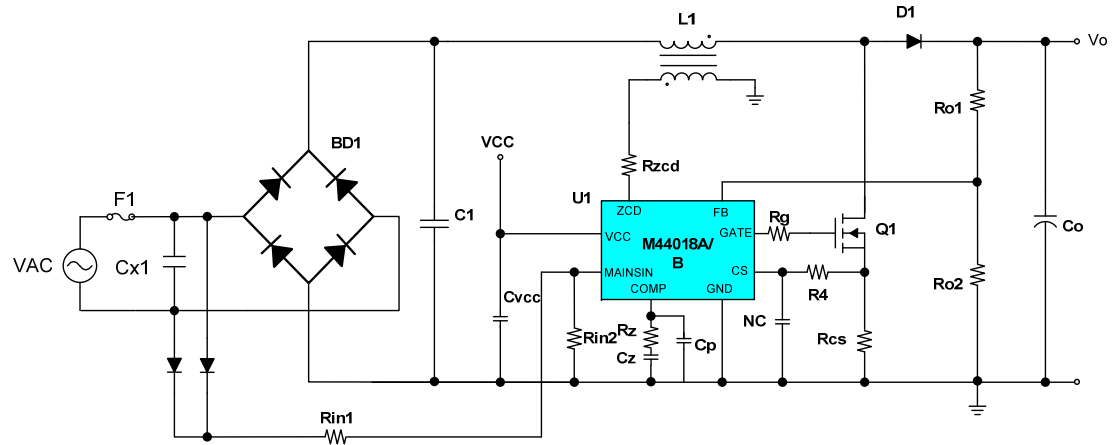
# MP44018-A

## 特点

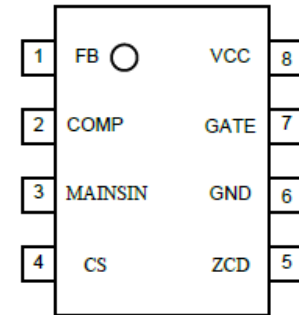
- **CrM/DCM**控制方式
- 超低的待机功耗 **<30mW**
- 快速的动态响应
- 谷底开通减小开关损耗
- 轻载降频减小开关损耗
- 待机模式下供电电流非常低
- 工作在打突发模式下软开关以及软关断技术可以减小噪声
- 线电压补偿可以实现很好线电压跳变及相同的过载保护点
- THD优化
- 全面的保护（欠压保护、过呀保护，过流保护，输入欠压保护，FB开路以及短路保护）



## 典型应用电路



### TOP VIEW

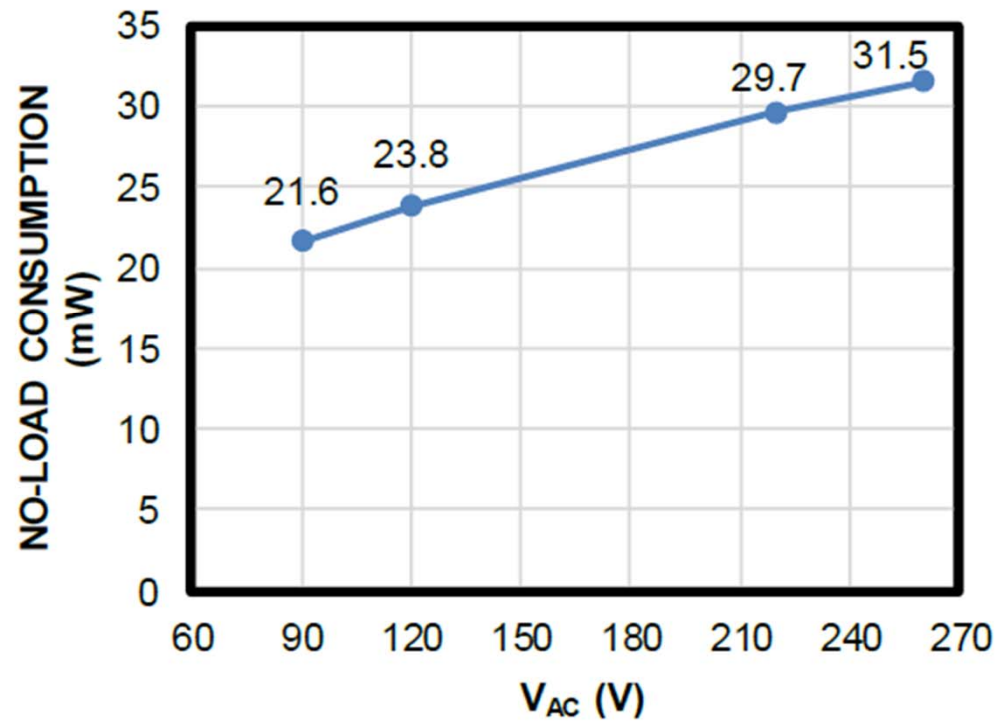


### SOIC-8封装

# MP44018-A 空载损耗

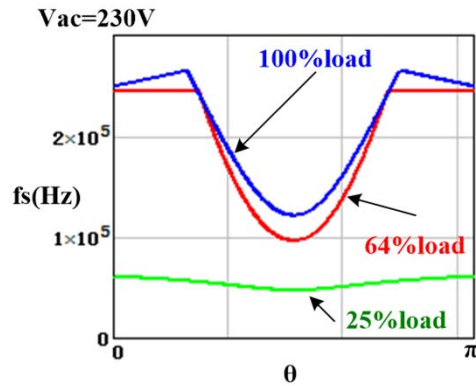
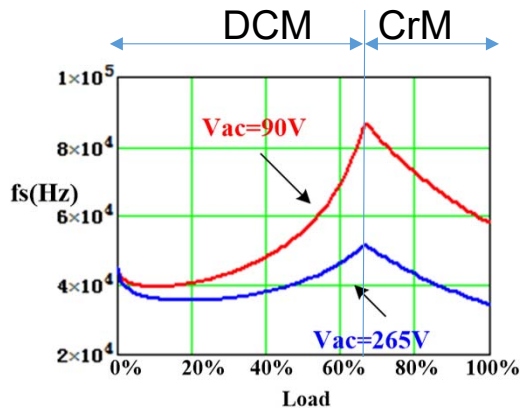
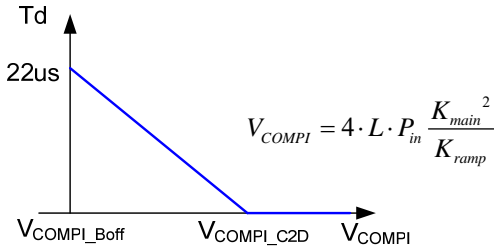
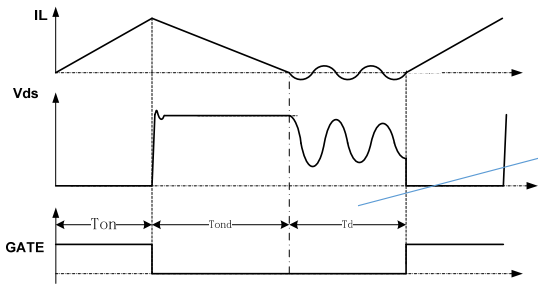
$V_{in}=85-265VAC$   $V_{out}=400V$

No-Load Consumption

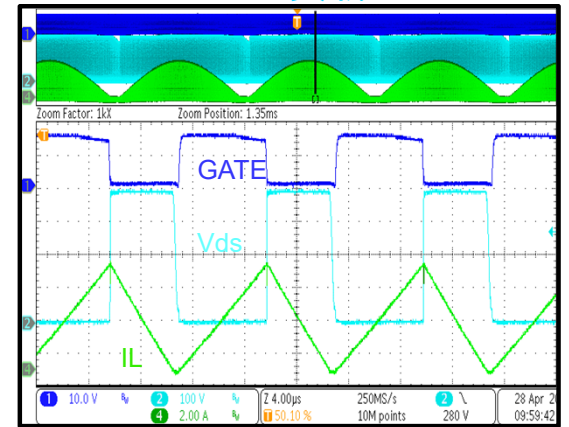


# MP44018-A 空载损耗

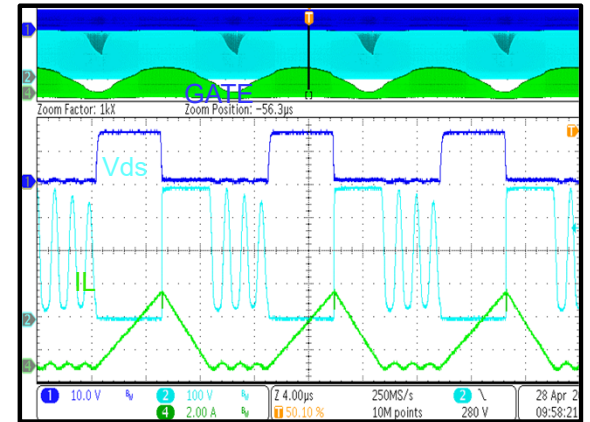
- 1) 在重载，MP44018-A工作在临界导通模式，此时主要是导通损耗
- 2) 随着负载变轻，开关损耗渐渐占据主导，MP44018A通过死区延伸技术由临界导通模式切换到断续模式
- 3) 不管是在临界还是在断续，MP44018-A都是谷底导通来降低开关损耗



100%负载



50%负载



# MP44018-A 优越的动态性能

传统PFC的带宽在10Hz以下，抑制工频纹波，减小电感电流的THD。但是动态响应比较差。

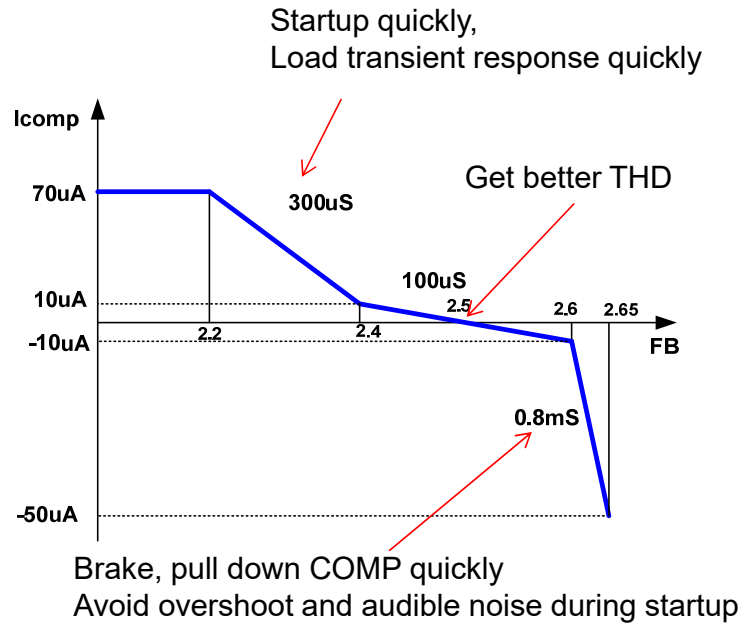
## 主电路补偿

$$\left\{ \begin{aligned} P_{in} &= \frac{V_{ac}^2}{2L} \cdot T_{on} \\ T_{on} &= C_{ramp} \frac{V_{comp}}{i_{ramp}} \\ i_{ramp} &= kV_{ac}^2 \end{aligned} \right.$$

MP44018 contains a square of Vac compensation circuit.

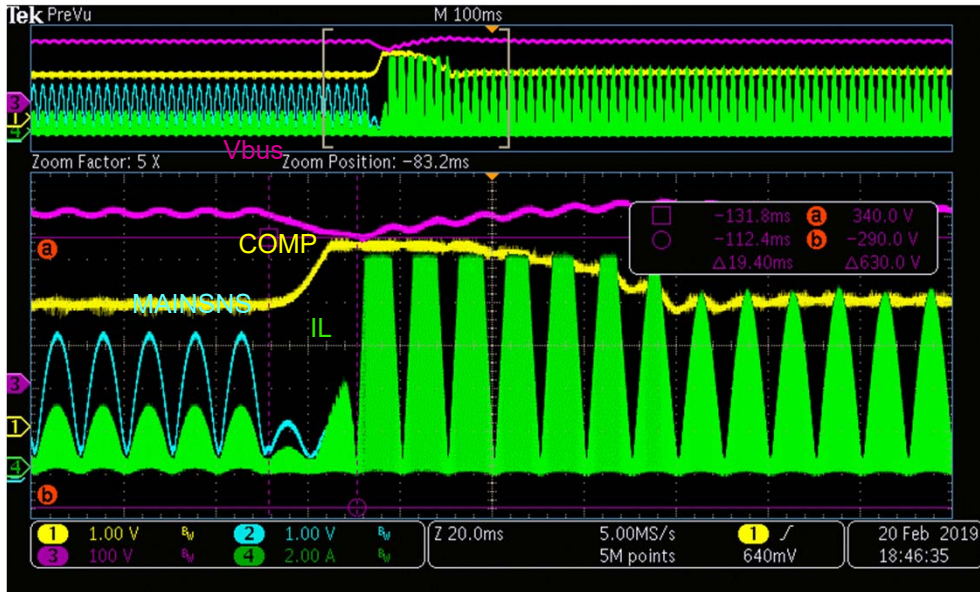
$$\rightarrow P_{in} = \frac{V_{ac}^2}{2L} \cdot C_{ramp} \frac{V_{comp}}{kV_{ac}^2}$$

## 非线性增益设计



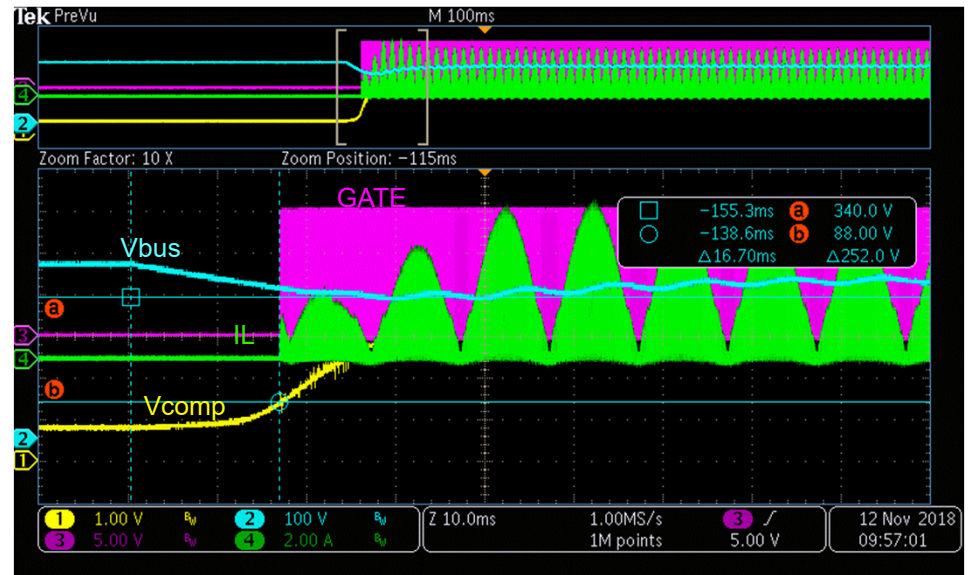
# MP44018-A输入线性跳变和负载跳变

输入电压跳变  
260VAC→90VAC/满载



Vbus min=340V

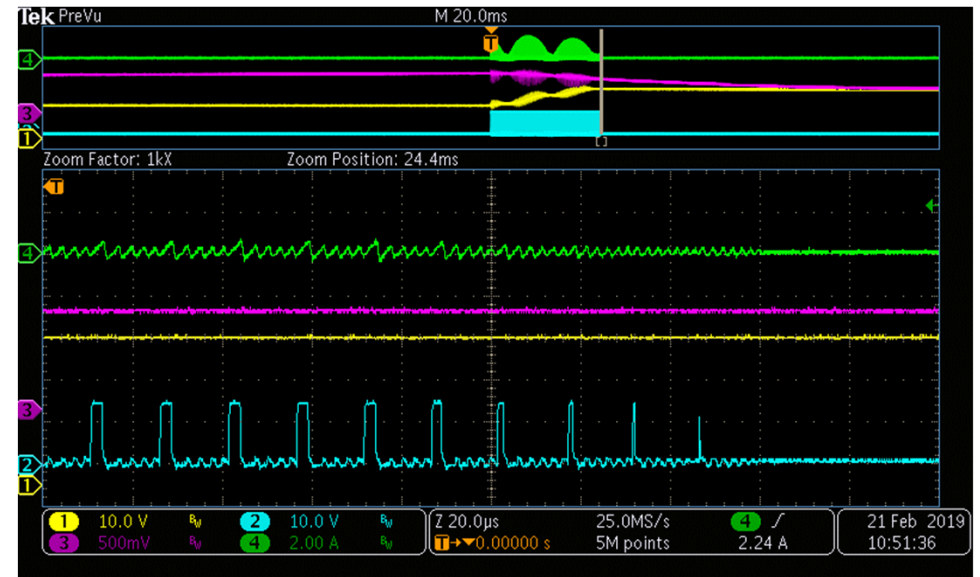
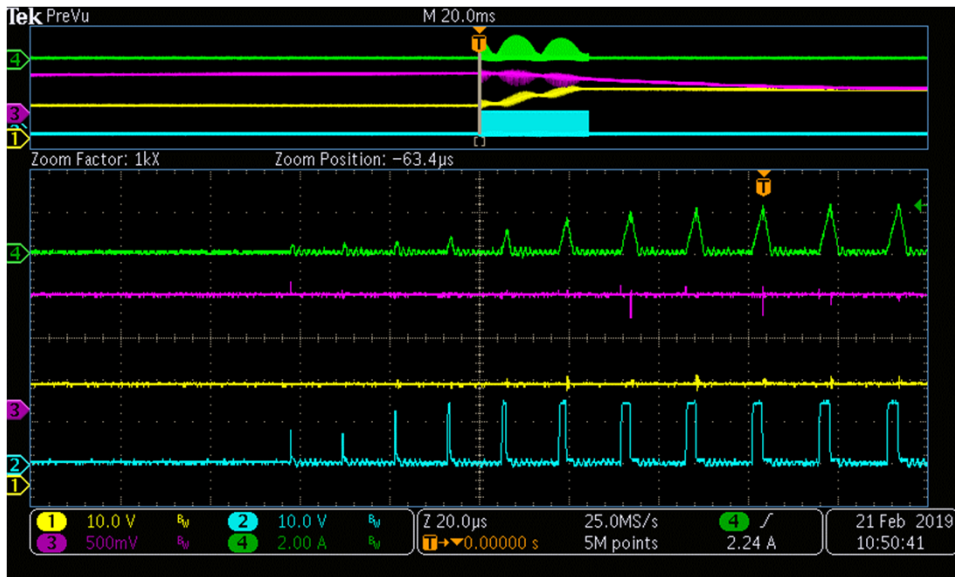
负载跳变  
空载→满载



Vbus min=340V

# MP44018-A 较小的噪音

## MP44018-A工作在轻载



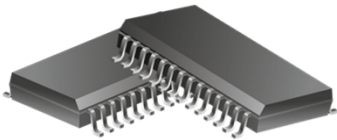
✓ Burst模式下MP44018-A有软启动和软关断功能，这样可以避免电感电流突变，避免了噪音。

# 数字型PFC+LLC COMB方案

# HR12xx –Family Tree, up to 1kW

## HR120x

Digital PFC + Analog LLC  
SOIC/TSSOP 28



Voltage mode LLC  
CCM/DCM PFC  
<150mW No load Power

## HR121x

Full Digital PFC + LLC  
SOIC/TSSOP 20



Current Mode LLC  
Improved Light Load Performance  
<100mW No Load Power

## HR122x

Full Digital PFC + LLC  
SOIC/TSSOP 20



Next Gen, Coming Soon.....

2016

2018

2020

2021

Released

Sampling

Design



# HR1211 – 数字型PFC+LLC 2合1的控制器

## 主要特点

### 系统概述

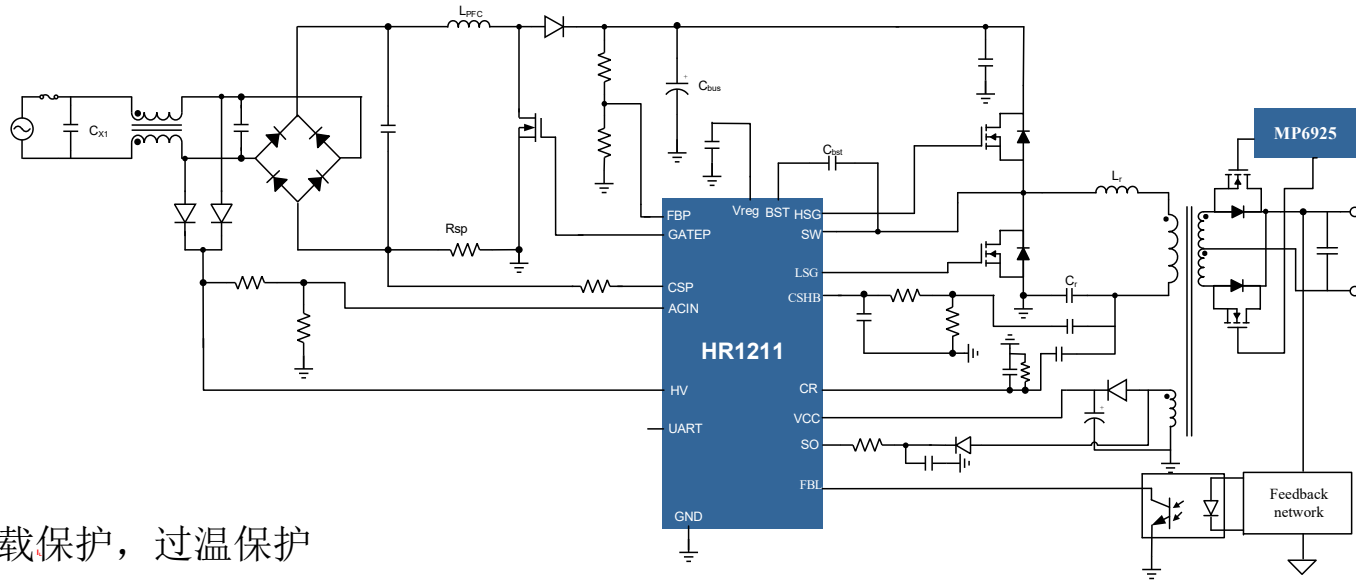
通过GUI进行数字可编程控制

- <100mW 待机功耗
- 轻载有较高的效率  
- > 80%@ 5W, > 65%@0.5W
- 全面的保护

欠压保护, 过压保护, 过流保护, 过载保护, 过温保护

### PFC部分

- 高压启动以及集成X-cap放电
- CCM和DCM多模式控制
- PF补偿, PF容易获得>0.9 在10%负载
- 两级数字环路补偿



### LLC部分

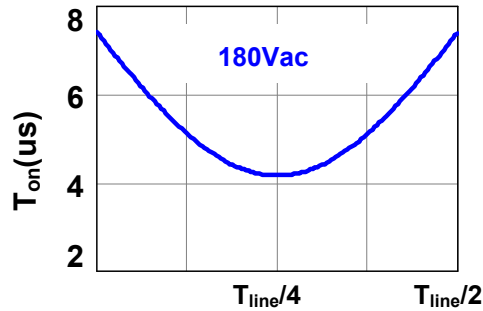
- 集成600V半桥驱动
- 电流模式控制
- 专有的突发和跳变工作模式
- 可变死区和容性保护

# HR1211 – 数字型PFC+LLC 2合1的控制器

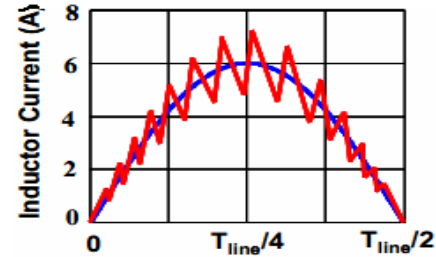
控制原理:

$$T_{ON}(t) = \frac{V_{out} - V_{in}(t)}{V_{out}}$$

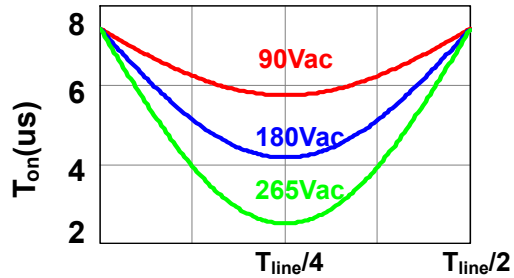
$T_{on}$  vs Load



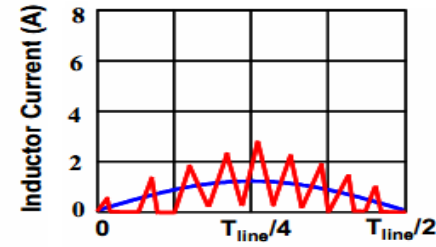
Full Load CCM



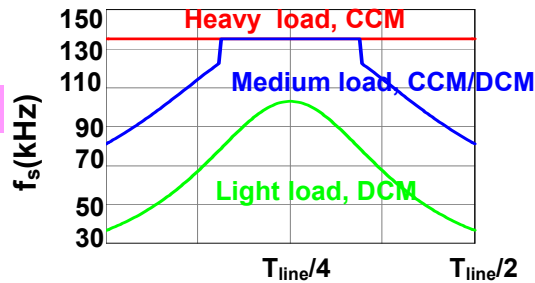
$T_{on}$  vs  $V_{in}$



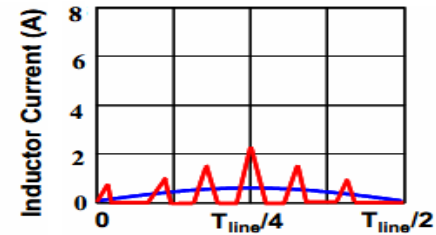
Medium Load CCM/DCM



$f_s$  vs ( $V_{in}$  or Load)

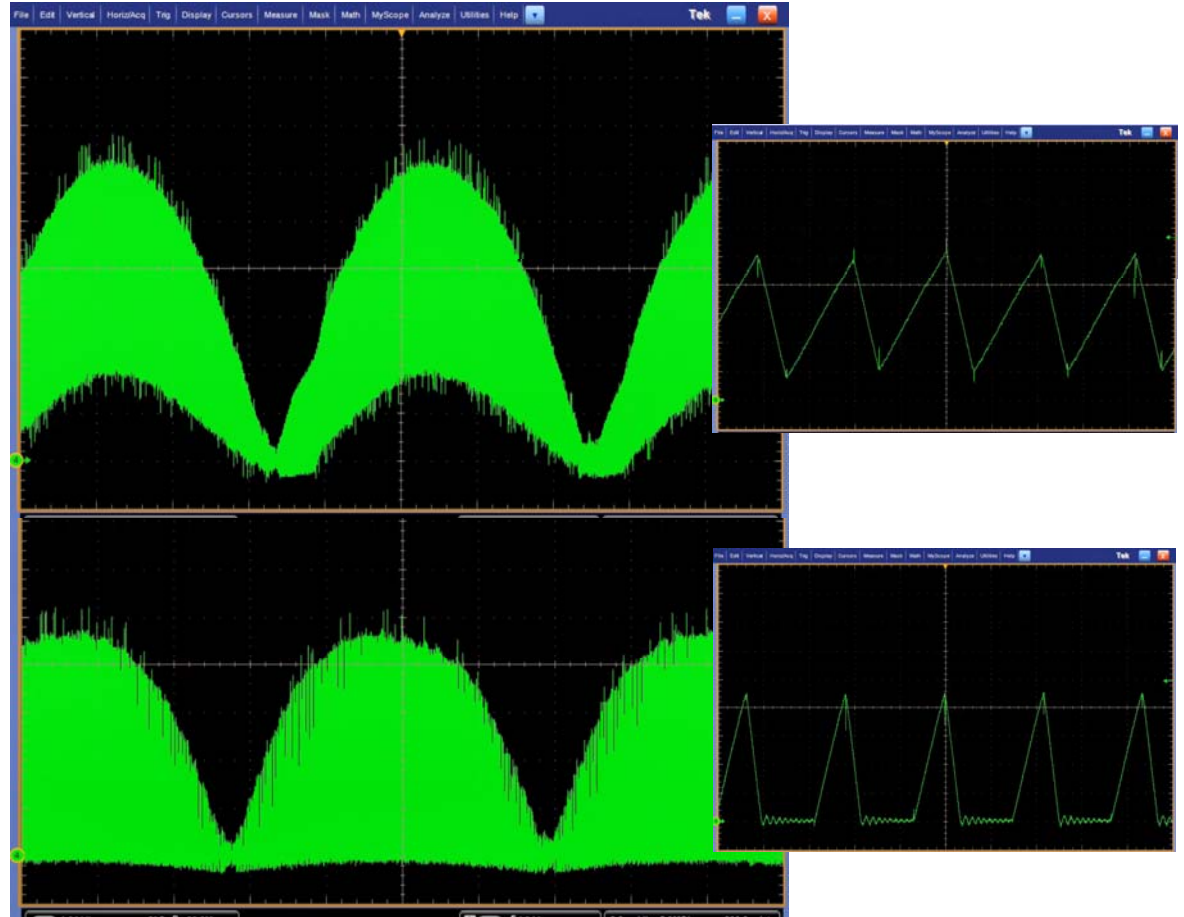
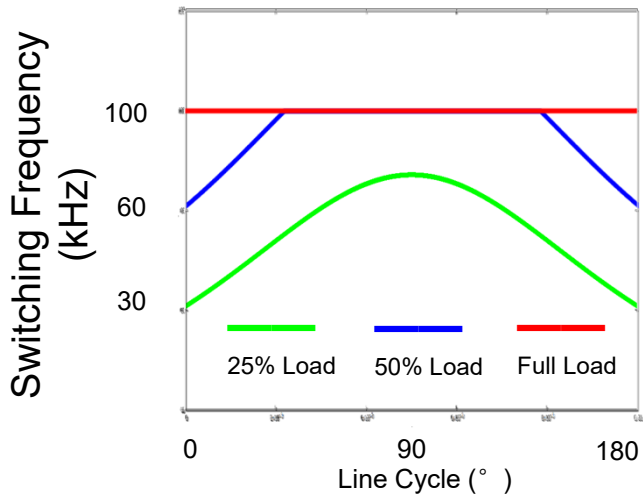
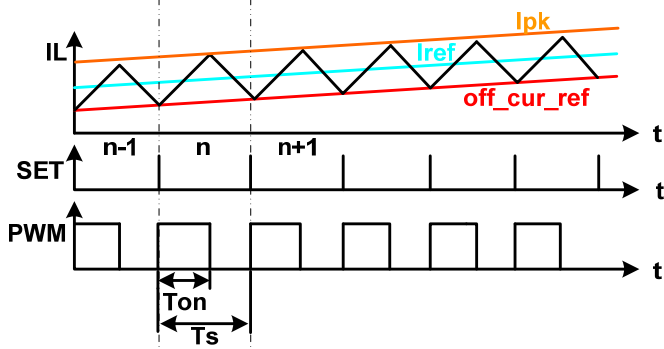


Light Load DCM



# HR1211 – 数字型PFC+LLC 2合1的控制器

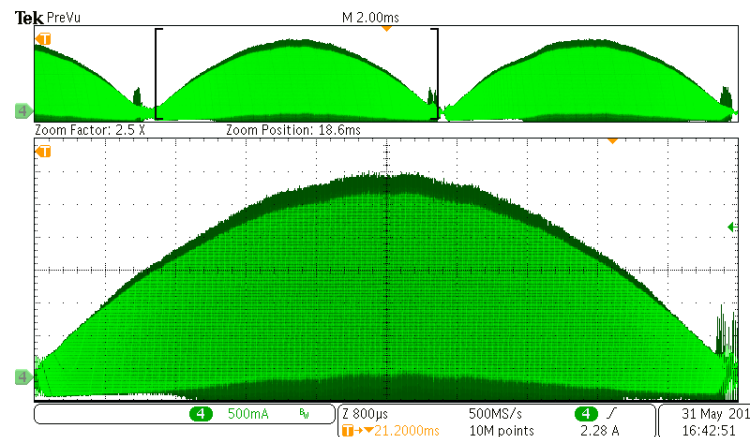
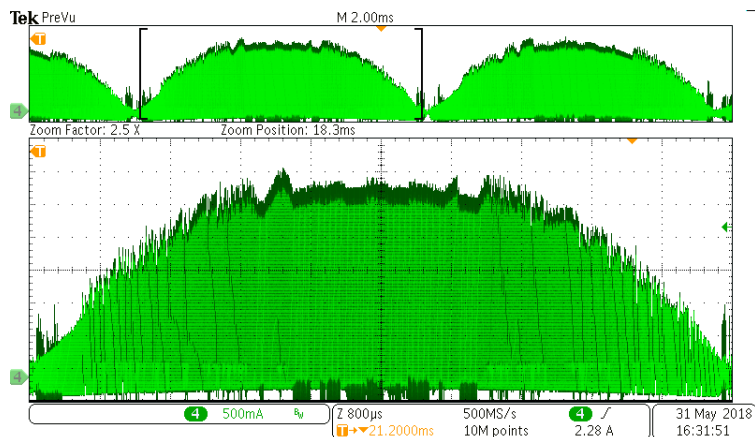
## CCM&DCM PFC Control



# HR1211 – 数字型PFC+LLC 2合1的控制器

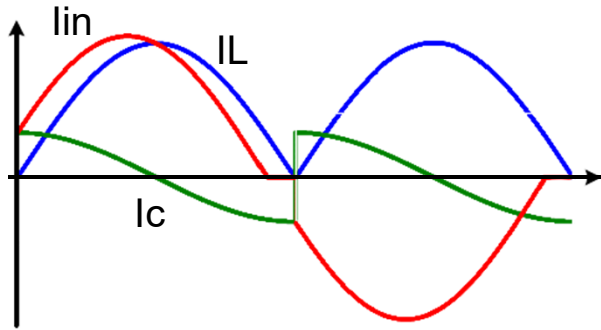
## 电流采样的数字滤波

<b>csp filter:</b>	<input checked="" type="checkbox"/> ON	<b>td filter:</b>	<input checked="" type="checkbox"/> ON
<b>csp filter stage:</b>	1st stage	<b>td filter stage:</b>	1st stage
<b>1st csp filter cross freq set:</b>	15	<b>1st td filter cross freq set:</b>	9
<b>2nd csp filter cross freq set:</b>	15	<b>2nd td filter cross freq set:</b>	15

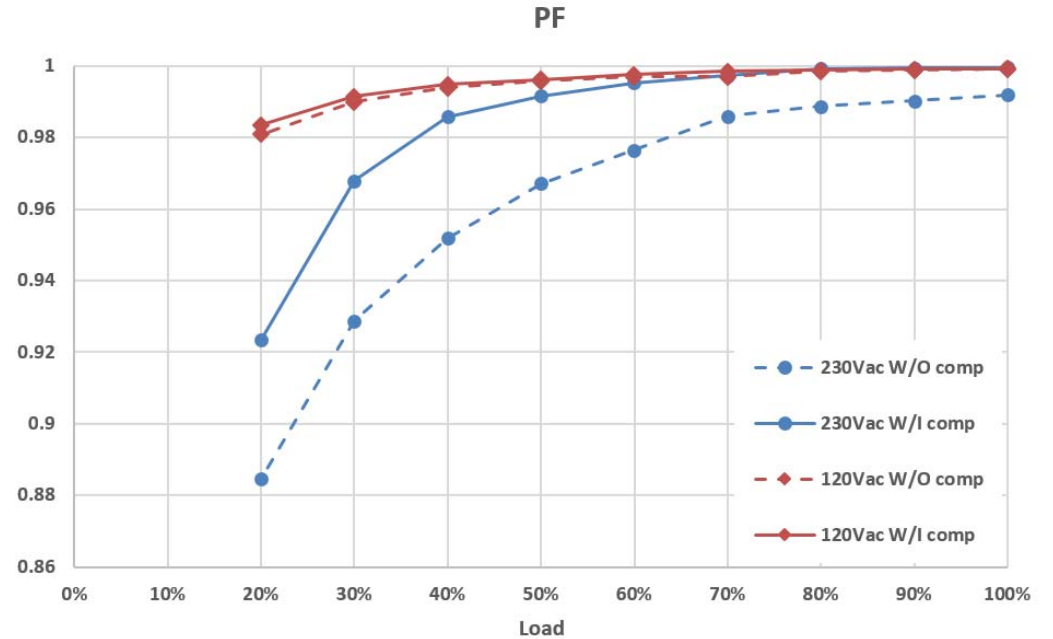
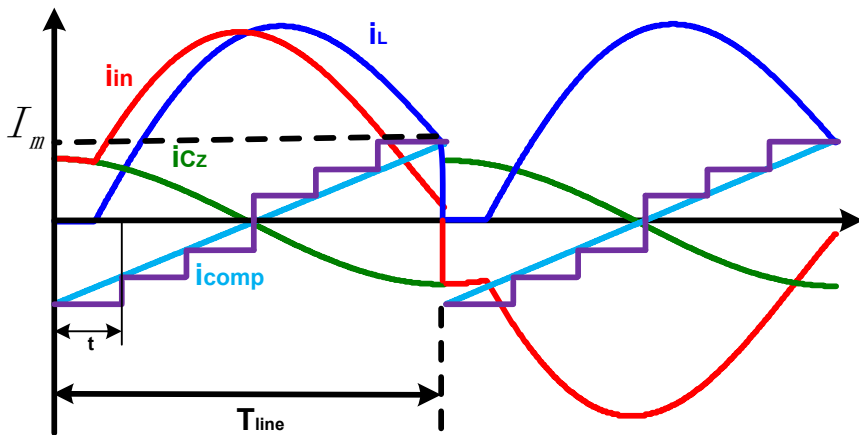


# HR121x – Digital PFC+ LLC Combo Controller

## PF补偿



$$\cos \varphi = \frac{P_{in} / U_{in}}{\sqrt{(P_{in} / U_{in})^2 + (U_{in} \times \omega C)^2}}$$

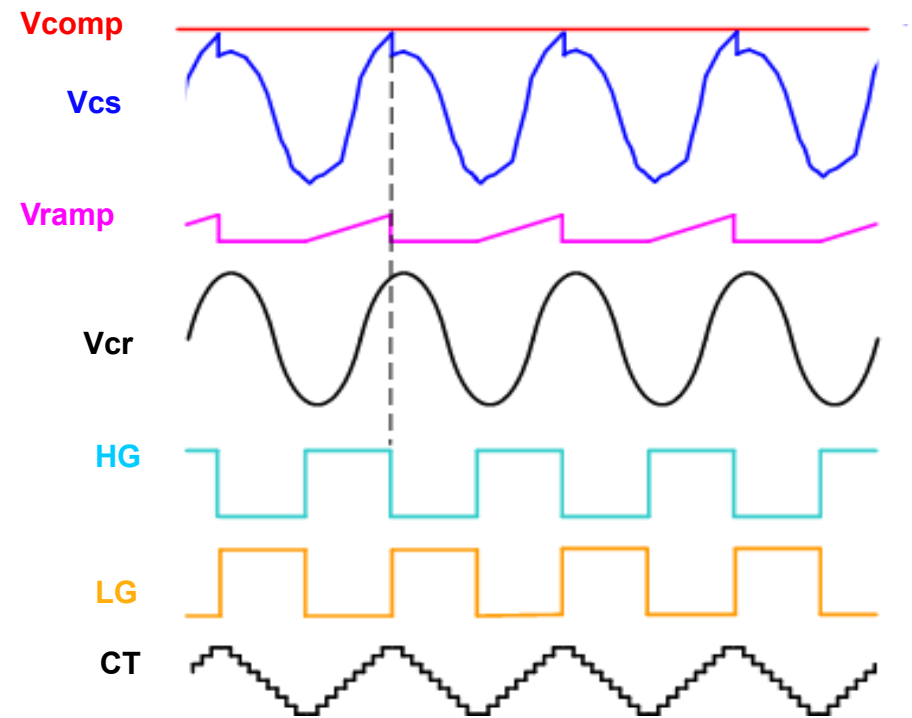
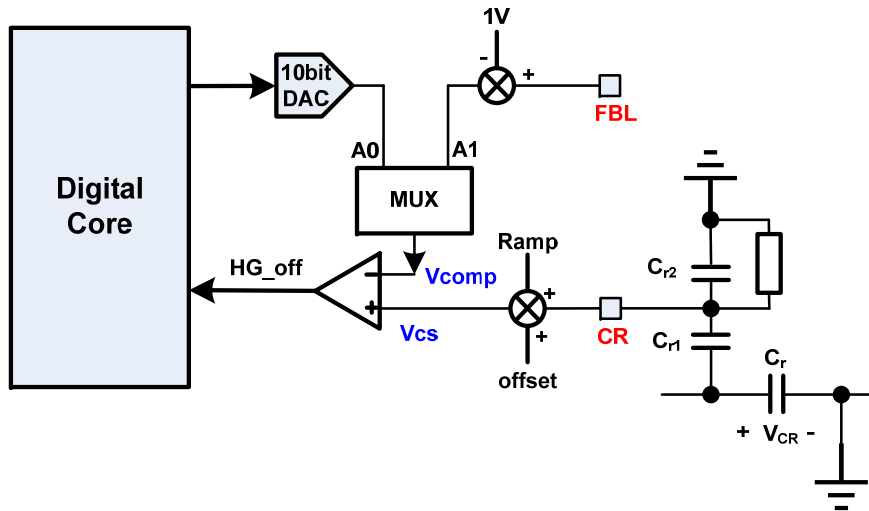


PF Compensation:  ON

	VIN-R1	VIN-R2	VIN-R3	VIN-R4
Input Voltage (Vrms):	85	150	220	265
Input Frequency (Hz):	60	60	50	50
Cap Compensation (%Cin):	30	50	80	100

# HR121x – Digital PFC+ LLC Combo Controller

## 电流模式LLC控制

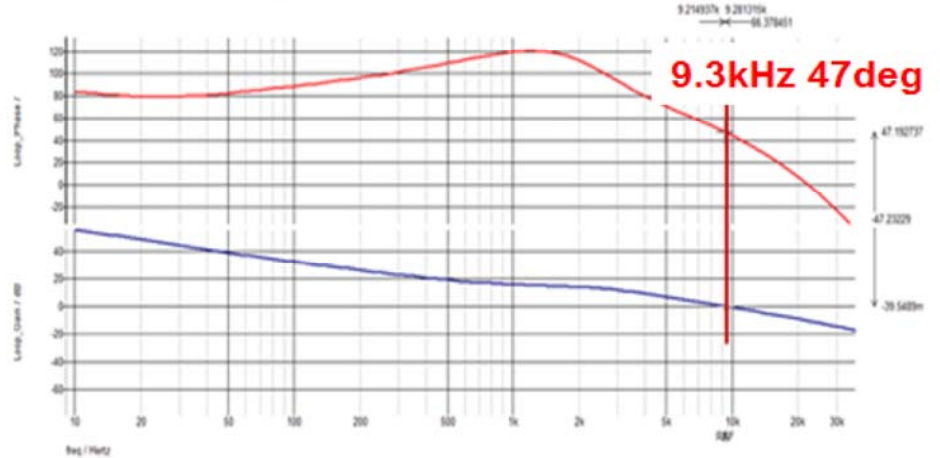
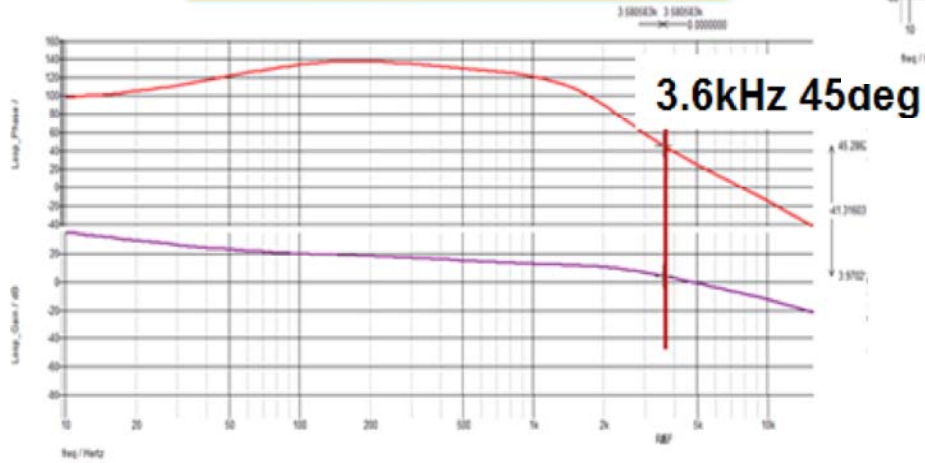


# HR121x – Digital PFC+ LLC Combo Controller

## Current Mode LLC Control

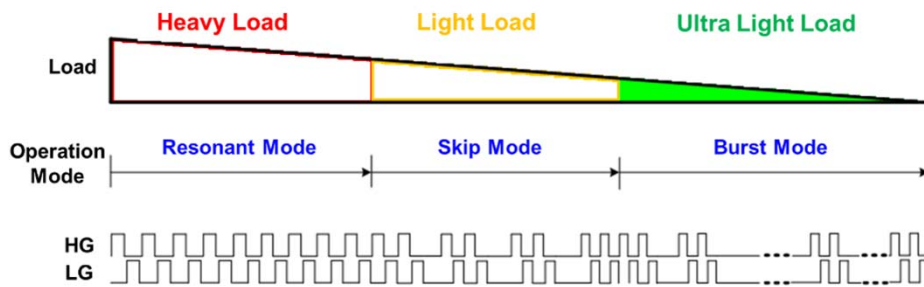
## LLC\_Current Mode Control

## LLC\_Voltage Mode Control



# HR121x – Digital PFC+ LLC Combo Controller

## Skip and Burst Modes for Light Load





# HR121x – Digital PFC+ LLC Combo Controller

## Burst Frequency Control

### Burst mode

Burst mode in level(FBL): 0.4 (V)

Burst mode in level(VComp): 0.18 (V)

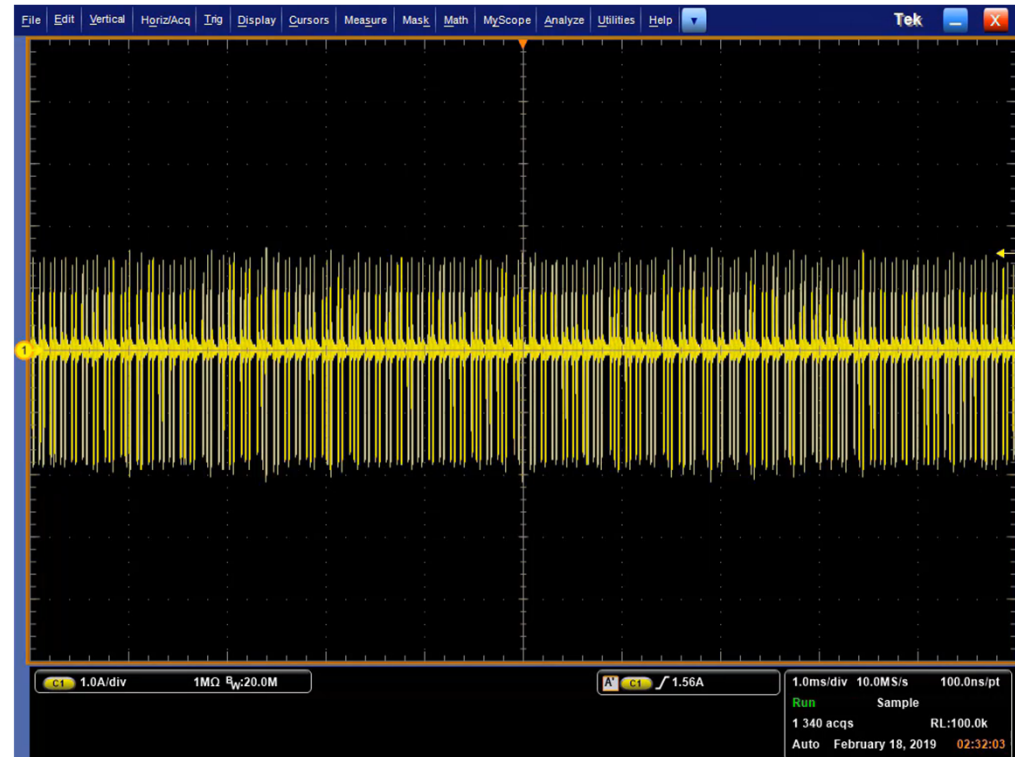
Burst mode hysteresis: 0.1 (V)

Burst frequency control:  ON

Max Burst frequency: 800 Hz

Min Burst frequency: 375 Hz

Burst frequency blanking period: 3



# HR121x – Digital PFC+ LLC Combo Controller

## 数字好处

- 通过GUI可以进行丰富的配置
- 可在任何阶段配置，从研发到成品专利保护

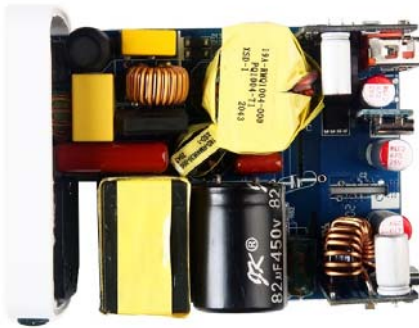


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# HR12xx Families Based Products



85W Laptop Adaptor



100W PD Adapter



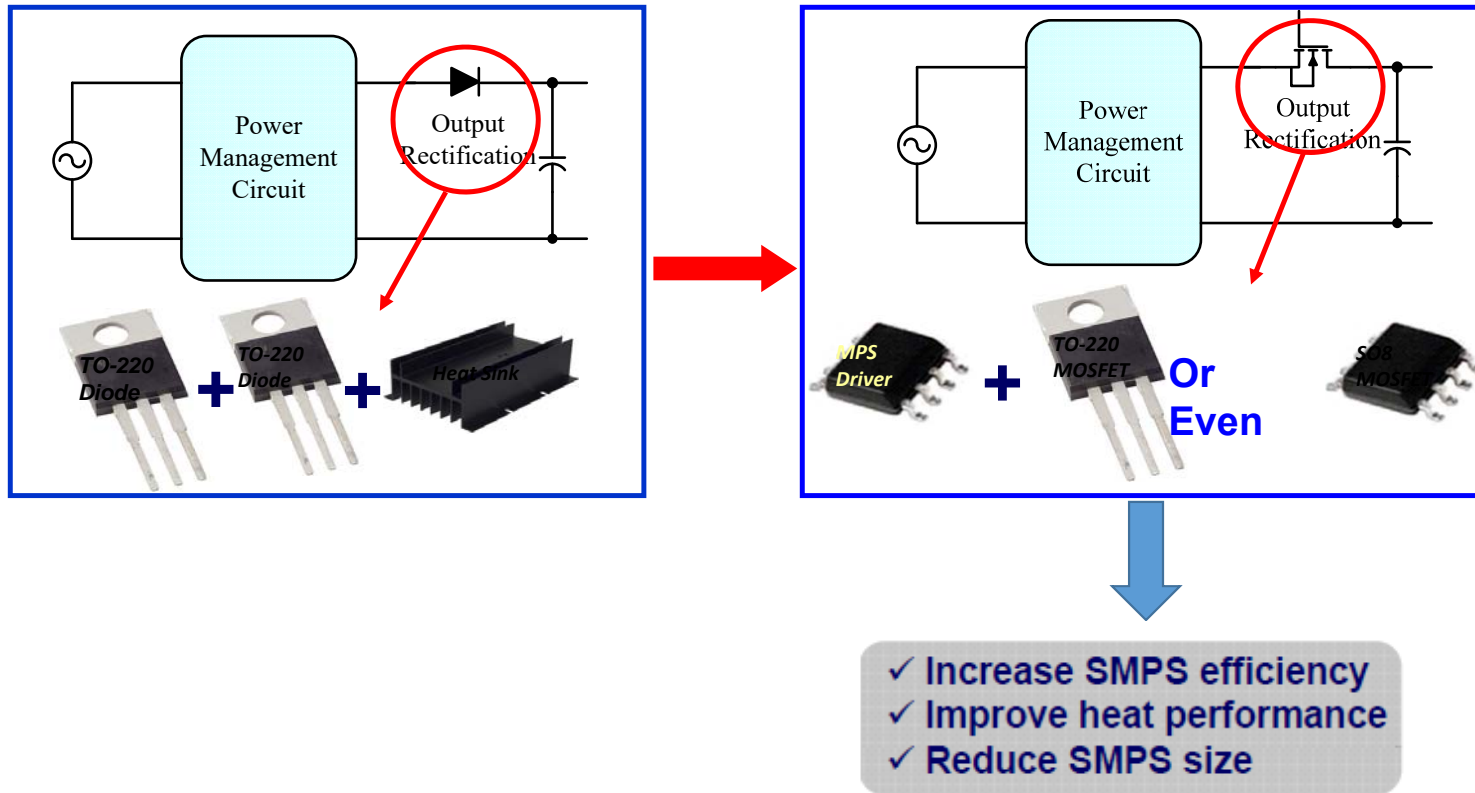
460W Desktop Power



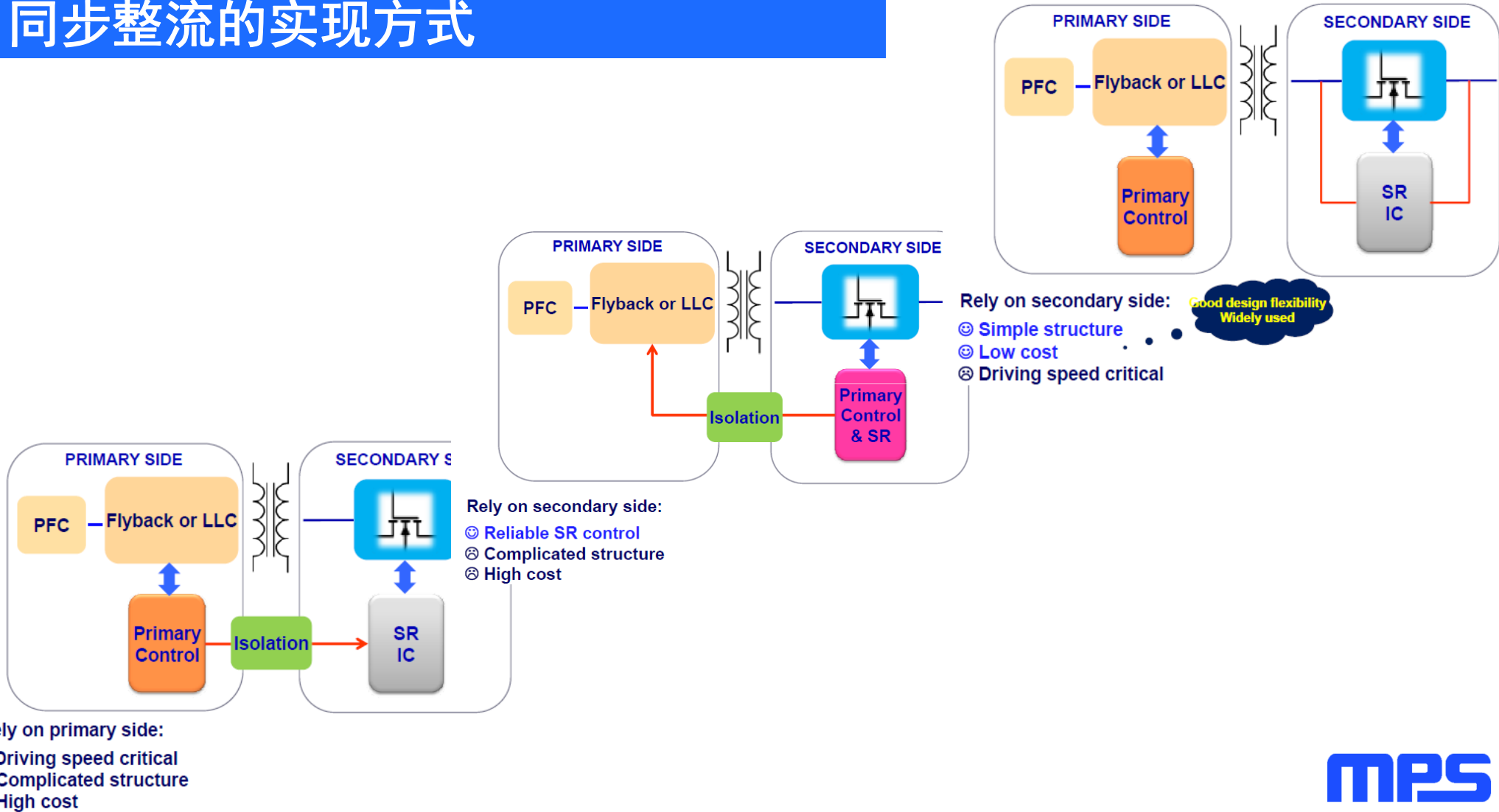
570W Server Power

# 高性能、高可靠的同步整流方案

# 应用场景-低压大电流输出

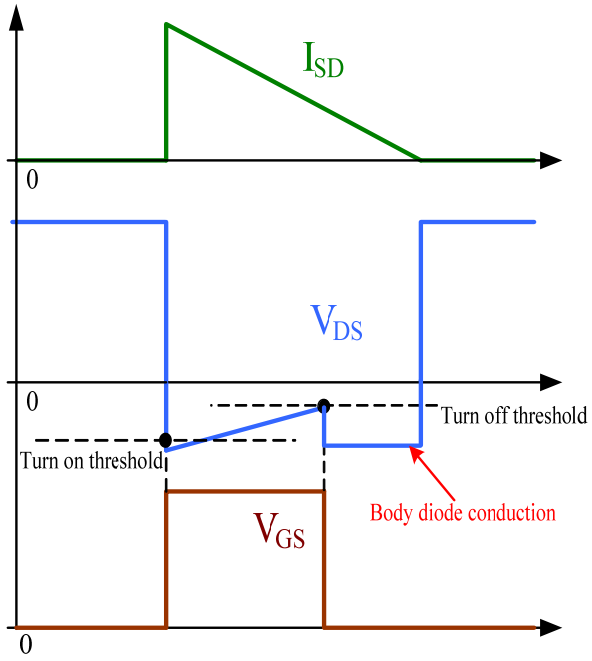


# 同步整流的实现方式

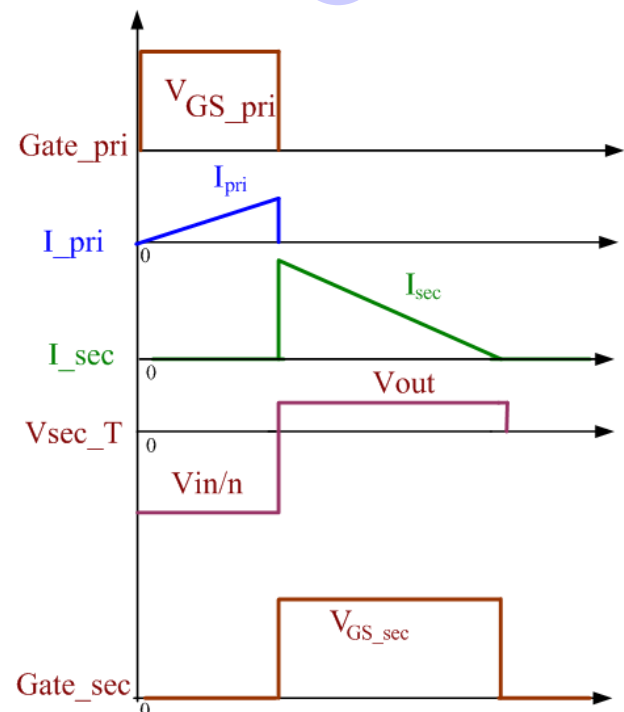


# 同步整流的控制方式

1

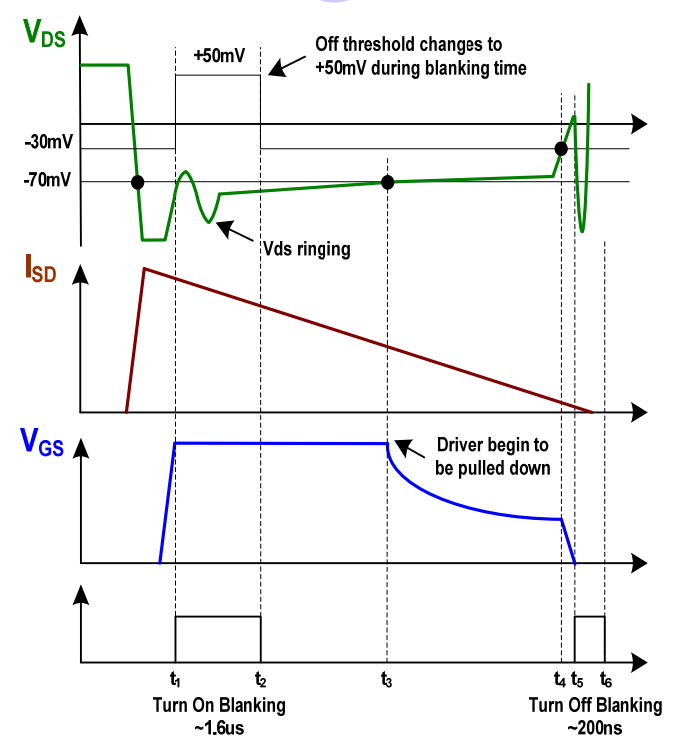


2

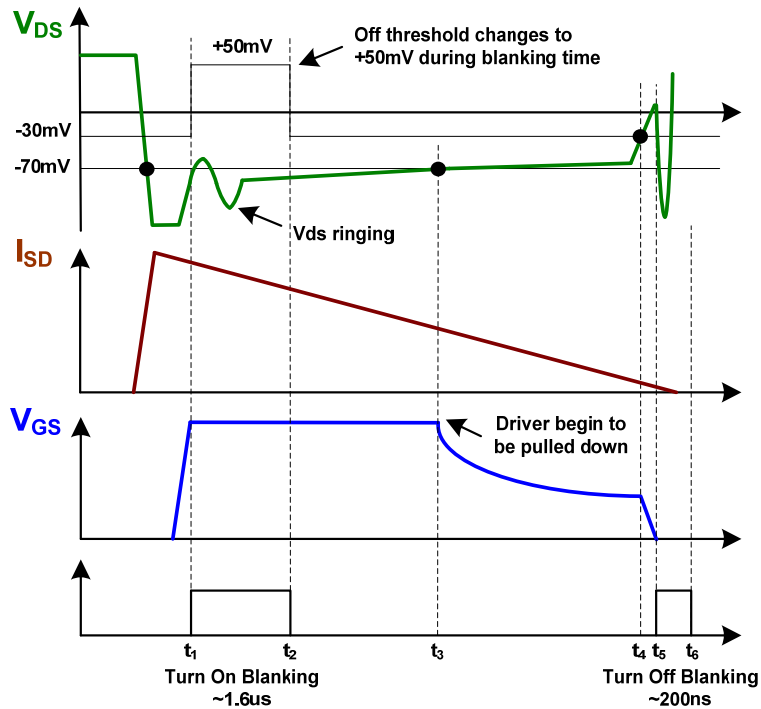


$$V_{in}/n \times T_{on} = V_{out} \times T$$

3



# MPS SR工作原理



**t1:** MPS SR通过采样Vds电压，一旦检测到Vds电压小于-70mV，就会开通MOS

**t1-t2:** 为了避免由于震荡引起的误关断，SR有个最小的导通时间

**t2-t3:** Vds小于-70mV，驱动电压一直维持在最大值

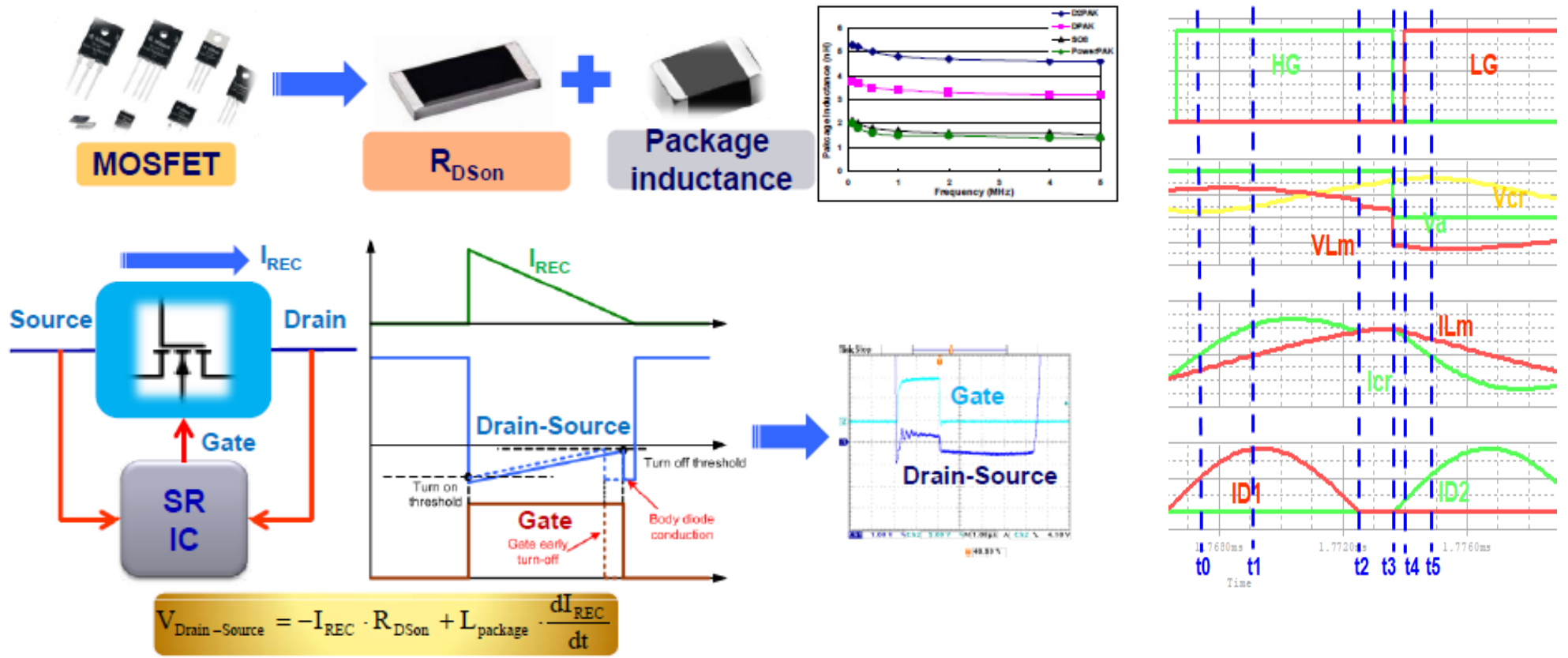
**t3-t4:** 一旦Vds电压大于-70mV，驱动电压开始调制从而使得Vds保持在-70mV附近

**t4-t5:** Vds一旦碰到关断阈值，驱动就会关断

**t5-t6:** 200ns最小的关断时间



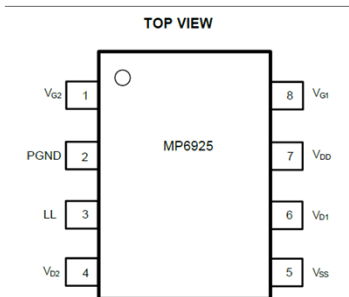
# SR应用常见遇到的问题



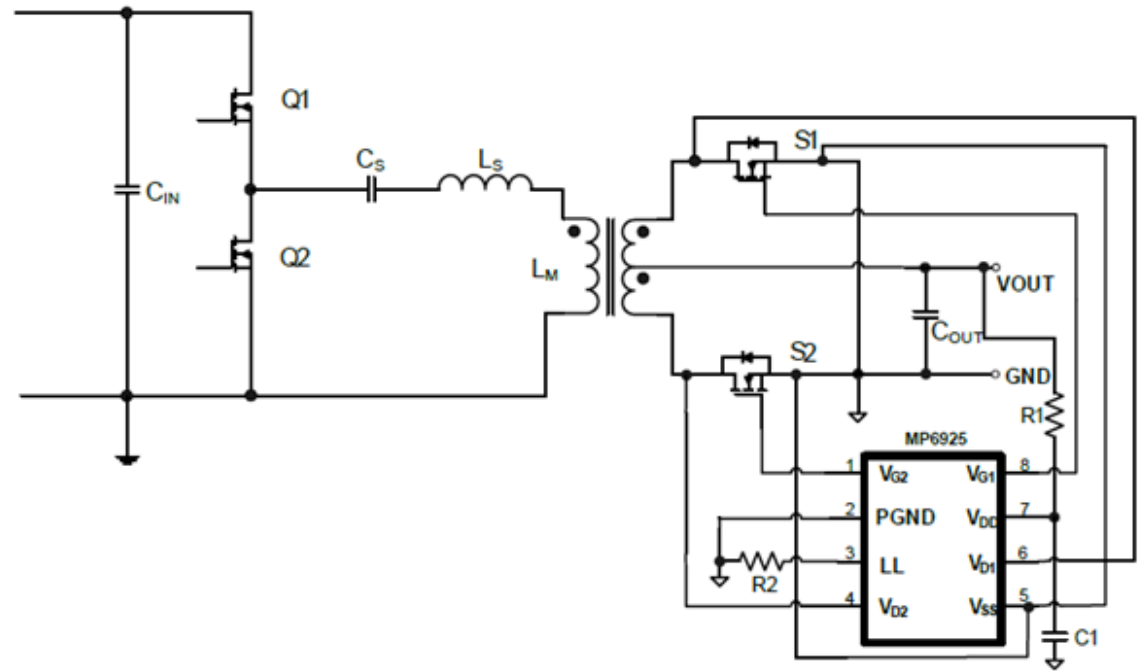
# MP6925 – LLC 同步整流

## 特点

- 快速关断, 总延时35ns
- 宽电压工作范围 (4.2-35V)
- **175 $\mu$ A** 低静态工作电流
- 支持CCM, DCM 和CRM
- 兼容能源之星

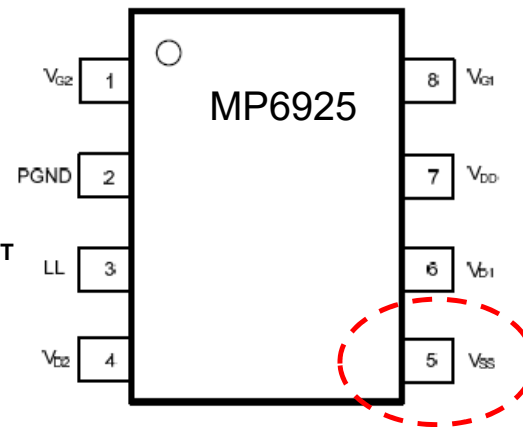
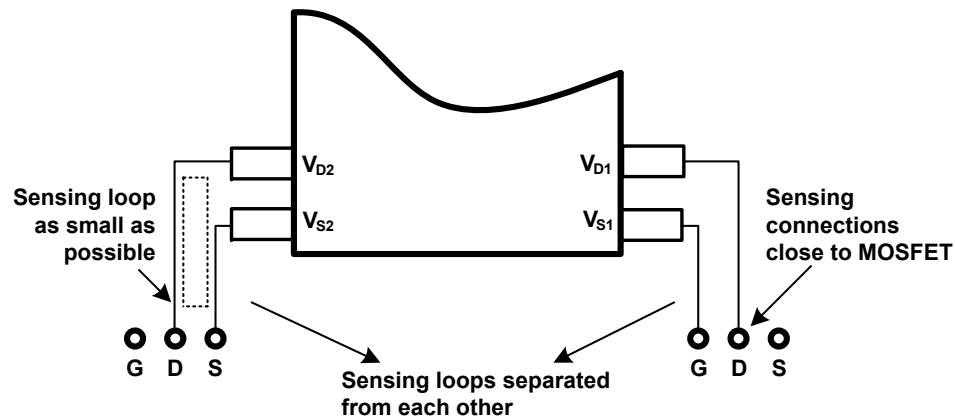


Available in an SOIC-8 Package



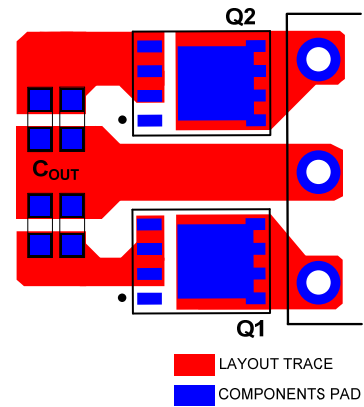
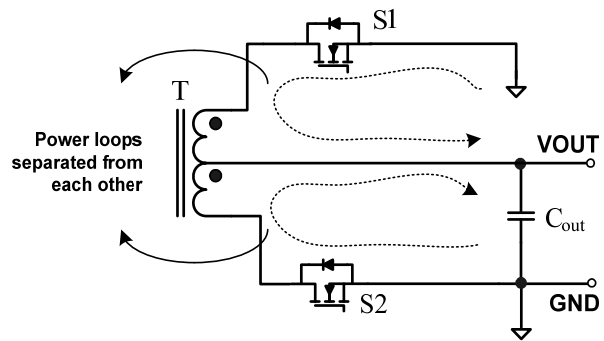
# 应用场景-布板的注意事项

## Sensing for $V_D/V_{SS}$



- ✓  $V_D/V_{SS}$ 采样必须尽量靠近MOS
- ✓ 保持两个MOS的采样通道独立，以及回路尽可能小
- ✓ SR芯片一定要放在功率回路外面，防止被干扰

# 应用场景-布板的注意事项



## 系统回路

✓尽可能减小功率回路,



# 谢谢

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